

Chapter 1 Time-Varying and Time-Harmonic Electromagnetic Fields

1.2 Maxwell's Equations

→ Actually, the work of many scientists - Faraday, Ampere, Gauss, Volta, Lenz, Coulomb, ... - that were combined into a set of equations by James Clerk Maxwell (Scottish physicist & mathematician)

1.2.1 Differential Form of Maxwell's Equations

→ describes relationships between fields and sources at any point in space at any time

→ Except where there are discontinuities in charge or current distributions, the fields are 'well behaved' - single-valued, bounded, & continuous functions of position & time w/ continuous derivatives.

$$\text{Faraday's Law} \quad \vec{\nabla} \times \vec{E} = -\vec{M}_i - \frac{\partial \vec{B}}{\partial t} = -\vec{M}_i - \vec{M}_d = -\vec{M}_t$$

$$\text{Ampere's Law} \quad \vec{\nabla} \times \vec{H} = \vec{J}_i + \vec{J}_c + \frac{\partial \vec{D}}{\partial t} = \vec{J}_{ic} + \frac{\partial \vec{D}}{\partial t} = \vec{J}_{ic} + \vec{J}_o = \vec{J}_t$$

$$\text{Gauss' Law} \quad \vec{\nabla} \cdot \vec{D} = \rho_v$$

$$\vec{\nabla} \cdot \vec{B} = \rho_m$$

1.2.1 conti

$\vec{E} \equiv$ electric field intensity vector (V/m)

$\vec{H} \equiv$ magnetic field intensity vector (A/m)

$\vec{D} \equiv$ electric flux density vector (C/m^2)

$\vec{B} \equiv$ magnetic flux density vector (Wb/m^2)

$\vec{J}_i \equiv$ impressed/source electric current density vector ($\frac{A}{m^2}$)

$\vec{J}_c \equiv$ conduction electric current density vector (A/m^2)

$\vec{J}_d \equiv$ displacement electric current density vector (A/m^2)
(Maxwell's key contribution)

$= \frac{\partial \vec{D}}{\partial t} \Rightarrow$ In dielectrics, it partly is the motion of bound charges, i.e., true current.
 \Rightarrow Early writings speak of 'ether' or 'aether' conducting or allowing movement of bound charges

$\vec{M}_i \equiv$ impressed/source magnetic current density vector ($\frac{V}{m}$)
 \rightarrow new addition (compared to undergraduate courses)
part of 'generalized' current to balance Maxwell's Eqs
 \rightarrow Not real, but can represent physical problems

$\vec{M}_d \equiv$ displacement magnetic current density vector ($\frac{V}{m}$)
 $= \frac{\partial \vec{B}}{\partial t} \Rightarrow$ named to balance the \vec{J}_d term

$\rho_{ev} \equiv$ electric charge density (C/m^3)

$\rho_{mv} \equiv$ magnetic charge density (Wb/m^3) \leftarrow Another New addition

1.2.1 conti.

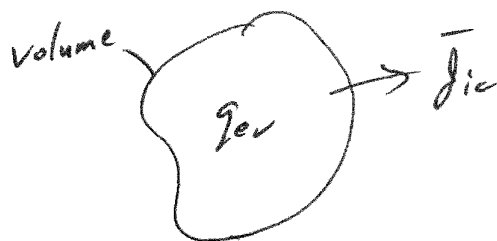
We can combine the impressed + conduction electric current densities into a single term, i.e.,

$$\bar{J}_{ic} = \bar{J}_i + \bar{J}_c \quad (A/m^2)$$

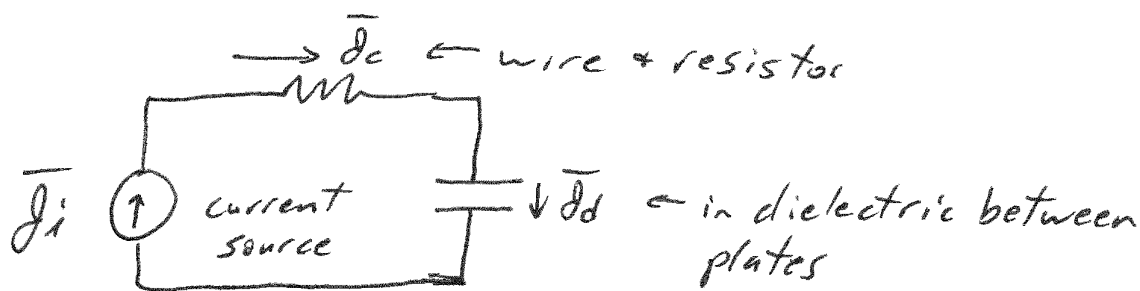
and, in turn, this can be related to the electric charge density by the continuity equation

$$\nabla \cdot \bar{J}_{ic} = - \frac{\partial \rho_{ev}}{\partial t}$$

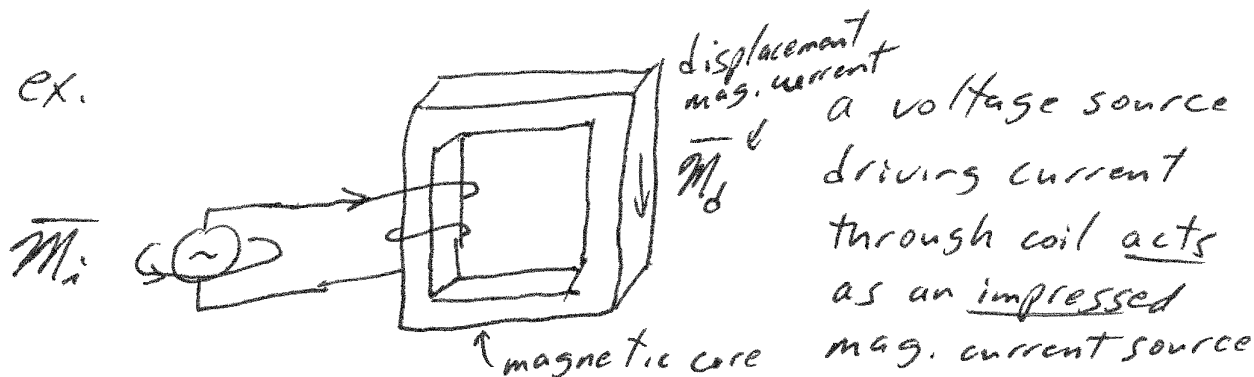
→ relates the net flow of current out of a small volume to the decrease in electric charge w/in the volume.



ex.



ex.



1.2.2 Integral Form of Maxwell's Eqs

→ describes inter-relationships between fields and sources over extended region of space

→ typically can only be analytically solved for highly symmetric problems

→ fields + derivatives of fields do not need continuous distributions

→ Use Stokes's Theorem $\oint_C \vec{A} \cdot d\vec{\ell} = \iint_S (\vec{\nabla} \times \vec{A}) \cdot d\vec{S}$
and

Divergence Theorem $\oiint_S \vec{A} \cdot d\vec{S} = \iiint_V \vec{\nabla} \cdot \vec{A} \, dV$

to integrate differential forms of Maxwell's Equations to get

Faraday's Law $\oint_C \vec{E} \cdot d\vec{\ell} = - \iint_S \vec{M}_i \cdot d\vec{S} - \frac{\partial}{\partial t} \iint_S \vec{B} \cdot d\vec{S}$

⇒ w/out \vec{M}_i , this equation tells us the open-circuit emf is related to time rate of decrease of mag. flux

Ampere's Law

$$\oint_C \vec{H} \cdot d\vec{\ell} = \iint_S \vec{J}_{ic} \cdot d\vec{S} + \frac{\partial}{\partial t} \iint_S \vec{D} \cdot d\vec{S} = \iint_S \vec{J}_{ic} \cdot d\vec{S} + \iint_S \vec{J}_d \cdot d\vec{S}$$

→ Tells us the line integral of \vec{H} is equal to current enclosed by closed path C .

1.2.2 cont.

Gauss' Law $\oiint_S \vec{D} \cdot d\vec{s} = \iiint_V \rho_{ev} dv = Q_e$ script Q

⇒ Total electric flux through a closed surface is equal to total charge enclosed.

'Magnetic' Gauss' Law

$$\oiint_S \vec{B} \cdot d\vec{s} = \iiint_V \rho_{mv} dv = Q_m$$

⇒ Remember no magnetic charges have been found (yet), we are using fictitious mag. charges to represent some problems

Continuity Equation

$$\oiint_S \vec{J}_{ic} \cdot d\vec{s} = -\frac{\partial}{\partial t} \iiint_V \rho_{ev} dv = -\frac{\partial Q_e}{\partial t}$$

1.3 Constitutive Parameters and Relations

⇒ Help us to describe how EM fields interact w/ matter/charged particles

⇒ More extensive discussion/coverage in Chap 2.

In the time-domain

$$\textcircled{1} \quad \bar{D} = \hat{\epsilon} * \bar{E} \quad * \equiv \text{convolution}$$

$\hat{\epsilon} \equiv \text{time-varying electric permittivity}$

⇒ If $\hat{\epsilon}$ is a constant, ϵ , then, $\bar{D} = \epsilon \bar{E}$

⇒ Free space $\hat{\epsilon} = \epsilon_0 = 9.8541878 \times 10^{-12} \text{ F/m}$
 (NOT $\frac{10^{-9}}{36\pi} \text{ F/m}$)

In the time-domain

$$\textcircled{2} \quad \bar{B} = \hat{\mu} * \bar{H} \quad \text{where } \hat{\mu} \equiv \text{time-varying magnetic permeability}$$

⇒ If $\hat{\mu}$ is a constant, μ , then, $\bar{B} = \mu \bar{H}$

⇒ Free space $\hat{\mu} = \mu_0 = 4\pi \times 10^{-7} \text{ H/m}$

In the time-domain

$$\textcircled{3} \quad \bar{J}_c = \hat{\sigma} * \bar{E} \quad \text{where } \hat{\sigma} \equiv \text{time-varying elec. conductivity}$$

⇒ If $\hat{\sigma} = \sigma$ (constant) $\bar{J}_c = \sigma \bar{E}$

⇒ Free space $\hat{\sigma} = 0$

1.3 cont.

⇒ These three equations are called the constitutive relations and $\bar{\epsilon}$, $\bar{\mu}$, + $\bar{\sigma}$ are called the constitutive parameters

⇒ In the frequency-domain, the convolution turns into a product, e.g.

$$\bar{D} = \epsilon \bar{E}$$

$$\bar{B} = \mu \bar{H}$$

$$\bar{J}_c = \sigma \bar{E}$$

Note: ϵ , μ , + σ can be complex!

⇒ Use the constitutive parameters to characterize / describe electrical / EM properties of materials, e.g., dielectrics, conductors, magnetic materials, ...

⇒ Linear vs nonlinear Do they depend on field strength?

⇒ homogenous vs inhomogenous Do they depend on location?

⇒ isotropic vs. anisotropic Do they depend on direction?

⇒ nondispersive vs. dispersive Do they depend on frequency?

1.4 Circuit-Field Relations

→ Relate Maxwell's equations to circuit quantities + equations

1.4.1 Kirchhoff's Voltage Law (KVL)

Start w/ the integral form of Faraday's Law

$$\oint_C \vec{E} \cdot d\vec{e} = - \iint_S \vec{M}_i \cdot d\vec{s} - \frac{\partial}{\partial t} \iint_S \vec{B} \cdot d\vec{s} \quad (\text{Field})$$

Note $\sum V_{\text{drops}} = \oint_C \vec{E} \cdot d\vec{e} \quad (V)$ voltage drops around circuit contour C

Assume $\vec{M}_i = 0$ (No impressed magnetic current densities)

Note: $\iint_S \vec{B} \cdot d\vec{s} = \Psi_m \equiv$ magnetic flux (Wb) (through surface enclosed by circuit)

Then $-\frac{\partial}{\partial t} \iint_S \vec{B} \cdot d\vec{s} = -\frac{\partial \Psi_m}{\partial t} = -\frac{\partial(Ls i)}{\partial t} = -Ls \frac{di}{dt}$

where $Ls \equiv$ stray inductance of the circuit (constant)

and $i \equiv$ current flowing around circuit

This yields:

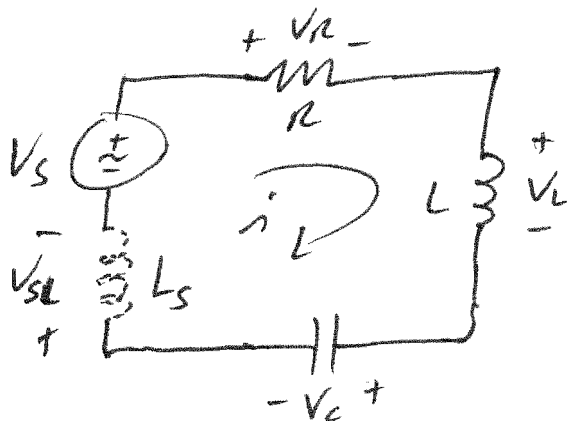
$$\sum V_{\text{drops}} = -\frac{\partial \Psi_m}{\partial t} = -\overbrace{Ls}^{V_{sL}} \frac{di}{dt} \quad (\text{Circuit})$$

At PC, we get $\sum V_{\text{drops}} = 0$

1.4.1 cont.

* Often, $L_S \approx 0$ or $\frac{di}{dt} \approx 0$ and we use
The DC form of KVL

ex.

Series RLC
circuit

$$\sum V_{\text{drops}} = -V_S + V_R + V_L + V_C = -V_{SL} = -L_S \frac{di}{dt}$$

1.4.2 Kirchhoff's Current Law (KCL)

Start w/ the integral continuity equation

$$\oint_S \vec{J}_{ic} \cdot d\vec{s} = -\frac{d}{dt} \iiint_V \rho_e dv = -\frac{dQ_e}{dt} \quad (\text{Field})$$

Note $\sum i_{\text{out}} = \oint_S \vec{J}_{ic} \cdot d\vec{s}$ (A) current passing
(leaving) through
closed surface S

Define $Q_e = C_S V$ where C_S is the stray capacitance
of the circuit

and V is the associated
voltage

1.4.2 cont.

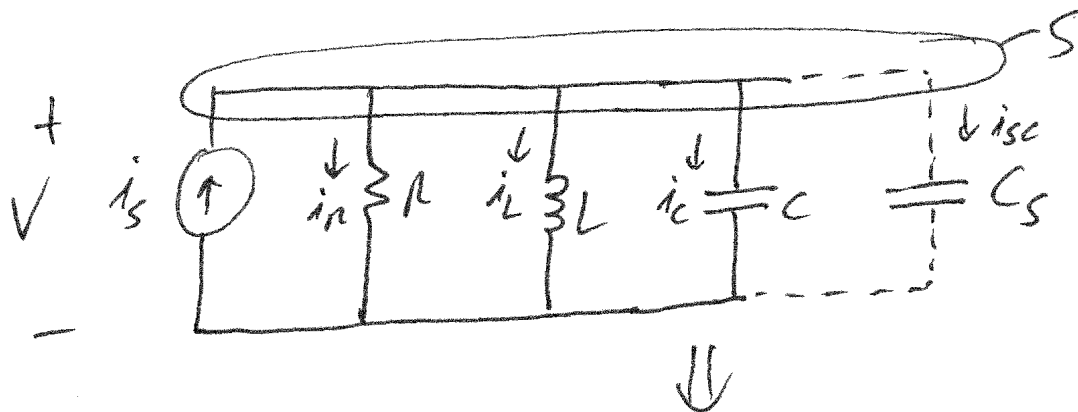
This yields:

$$\sum i_{out} = -\frac{dQ_e}{dt} = -\frac{d(C_S V)}{dt} = -C_S \frac{dV}{dt} \quad (\text{Circuit})$$

At DC, we get $\sum i_{out} = 0$ ↑
Includes displacement
current NOT through
wires.

* Often, $C_S \approx 0$ or $\frac{dV}{dt} \approx 0$ and we
use the DC form of KCL

ex. Parallel RLC circuit



$$\sum i_{out} = -i_s + i_R + i_L + i_C = -i_{sc} = -C_S \frac{dV}{dt}$$

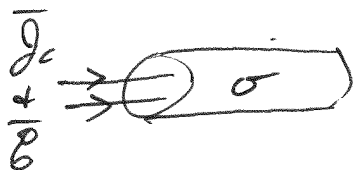
1.4.3 Element Laws

Besides KVL + KCL, we have relations between voltage + current for circuit elements

Ohm's Law / Resistor

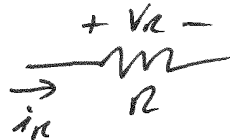
Field Relation
for conduction
current density

$$\bar{J}_c = \sigma \bar{E}$$



\Leftrightarrow Circuit Relation

$$i_R = \frac{1}{R} V_R = G V_R$$



Inductor Define $\Psi_m = L i$

Field Relation \Leftrightarrow Circuit Relation

$$\bar{B} = \mu \bar{H}$$

$$\Psi_m = L i$$

Then

$$\bar{M}_d = \frac{\partial \bar{B}}{\partial t} = \mu \frac{\partial \bar{H}}{\partial t}$$



and since $\frac{\partial}{\partial t} \iint_S \bar{B} \cdot d\bar{s} = \frac{\partial \Psi_m}{\partial t} = \underline{\underline{L \frac{\partial i}{\partial t} = V_L}}$

Field Relation

Circuit Relation

$$\bar{M}_d = \mu \frac{\partial \bar{H}}{\partial t}$$

$$\Leftrightarrow V_L = L \frac{\partial i}{\partial t}$$

1.4.3 cont

Capacitor Similar to the inductor

Field Relation

Circuit Relation

$$\vec{D} = \epsilon \vec{E}$$



$$Q_e = C V_e$$

$$\vec{J}_d = \epsilon \frac{\partial \vec{E}}{\partial t}$$



$$i_c = C \frac{dV_c}{dt}$$

TABLE 1-2 Relations between electromagnetic field and circuit theories

Field theory	Circuit theory
1. \mathcal{E} (electric field intensity)	1. v (voltage)
2. \mathcal{H} (magnetic field intensity)	2. i (current)
3. \mathcal{D} (electric flux density)	3. q_{ev} (electric charge density)
4. \mathcal{H} (magnetic flux density)	4. q_{mv} (magnetic charge density)
5. \mathcal{J} (electric current density)	5. i_e (electric current)
6. \mathcal{M} (magnetic current density)	6. i_m (magnetic current)
7. $\mathcal{J}_d = \epsilon \frac{\partial \mathcal{E}}{\partial t}$ (electric displacement current density)	7. $i = C \frac{dv}{dt}$ (current through a capacitor)
8. $\mathcal{M}_d = \mu \frac{\partial \mathcal{H}}{\partial t}$ (magnetic displacement current density)	8. $v = L \frac{di}{dt}$ (voltage across an inductor)
9. <i>Constitutive relations</i>	9. <i>Element laws</i>
(a) $\mathcal{J}_c = \sigma \mathcal{E}$ (electric conduction current density)	(a) $i = Gv = \frac{1}{R}v$ (Ohm's law)
(b) $\mathcal{D} = \epsilon \mathcal{E}$ (dielectric material)	(b) $Q_e = Cv$ (charge in a capacitor)
(c) $\mathcal{H} = \mu \mathcal{H}$ (magnetic material)	(c) $\psi = Li$ (flux of an inductor)
10. $\oint_C \mathcal{E} \cdot d\ell = -\frac{\partial}{\partial t} \iint_S \mathcal{H} \cdot ds$ (Maxwell-Faraday equation)	10. $\sum v = -L_s \frac{di}{dt} \simeq 0$ (Kirchhoff's voltage law)
11. $\iint_S \mathcal{J}_{tc} \cdot ds = -\frac{\partial}{\partial t} \iiint_V q_{ev} dv = -\frac{\partial Q_e}{\partial t}$ (continuity equation)	11. $\sum i = -C_s \frac{dv}{dt} \simeq 0$ (Kirchhoff's current law)
12. <i>Power and energy densities</i>	12. <i>Power and energy</i>
(a) $\iint_S (\mathcal{E} \times \mathcal{H}) \cdot ds$ (instantaneous power)	(a) $\mathcal{P} = vi$ (power-voltage-current relation)
(b) $\iiint_V \sigma \mathcal{E}^2 dv$ (dissipated power)	(b) $\mathcal{P}_d = Gv^2 = \frac{1}{R}v^2$ (power dissipated in a resistor)
(c) $\frac{1}{2} \iiint_V \epsilon \mathcal{E}^2 dv$ (electric stored energy)	(c) $\frac{1}{2} C v^2$ (energy stored in a capacitor)
(d) $\frac{1}{2} \iiint_V \mu \mathcal{H}^2 dv$ (magnetic stored energy)	(d) $\frac{1}{2} L i^2$ (energy stored in an inductor)

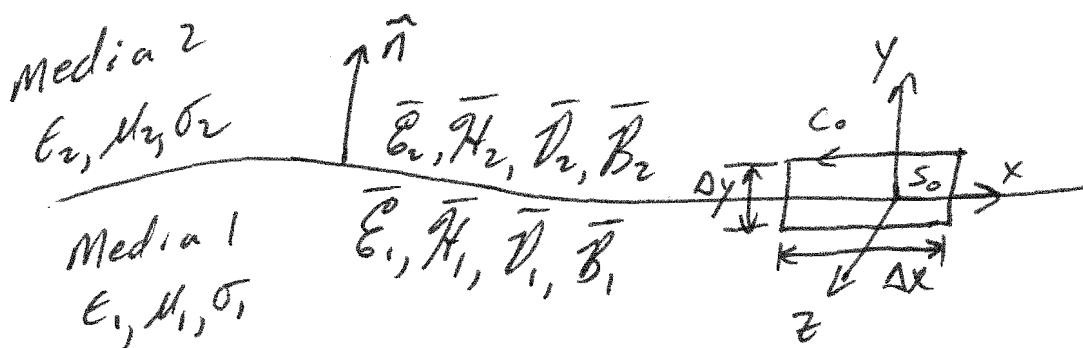
1.5 Boundary Conditions

⇒ What happens at the interface or boundary between materials/media w/ different electrical properties (σ, μ, ϵ)

⇒ Use integral form of Maxwell's Equations to derive boundary conditions

1.5.1 Finite Conductivity Media

Tangential



As shown, we have a rectangular contour C_0 bounding a surface area S_0 straddling the boundary. Further, we are locally going to assume the Cartesian coordinates shown.

* Assume no charges or sources at the boundary. (The no charges will be true assuming finite conductivities.)

1.5.1 cont.

First, let's apply Faraday's Law

$$\oint_{C_0} \vec{E} \cdot d\vec{e} = - \iint_{S_0} \vec{M}_i \cdot d\vec{s} - \frac{\partial}{\partial t} \iint_{S_0} \vec{B} \cdot d\vec{s}$$

Letting $\Delta y \rightarrow 0$ which implies $S_0 \rightarrow 0$

$$\begin{array}{c} \vec{E}_1 \cdot \hat{a}_x \Delta x \\ \text{(bottom)} \end{array} - \begin{array}{c} \vec{E}_2 \cdot \hat{a}_x \Delta x \\ \text{(top)} \end{array} = 0$$

Since the x-components of \vec{E}_1 + \vec{E}_2 are tangential (parallel) to the boundary,

$$\text{we get } E_{1x} \Delta x - E_{2x} \Delta x = 0$$

$$\hookrightarrow \underline{E_{1t} = E_{2t}} \quad \sigma_1 \text{ \& \& } \sigma_2$$

$$\text{OR } \underline{\hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0}$$

In words, the tangential electric field is continuous across the boundary between two finite conductivity media when there are no impressed magnetic current densities \vec{M}_i at the boundary.

\Rightarrow Tangential electric flux discontinuous $\frac{D_{1t}}{\epsilon_1} = \frac{D_{2t}}{\epsilon_2}$

1.5.1 cont.

Next, let's apply Ampere's Law w/ the assumption that there are no impressed sources at the boundary

$$\oint_{C_0} \vec{H} \cdot d\vec{e} = \iint_{S_0} \vec{J}_1 \cdot d\vec{s} + \iint_{S_0} \vec{J}_c \cdot d\vec{s} + \frac{\partial}{\partial t} \iint_{S_0} \vec{D} \cdot d\vec{s}$$

Again, let $\Delta y \rightarrow 0 \Rightarrow S_0 \rightarrow 0$

$$\vec{H}_1 \cdot \hat{a}_x \Delta x - \vec{H}_2 \cdot \hat{a}_x \Delta x = 0 + 0$$

$$H_{1x} \Delta x - H_{2x} \Delta x = 0$$

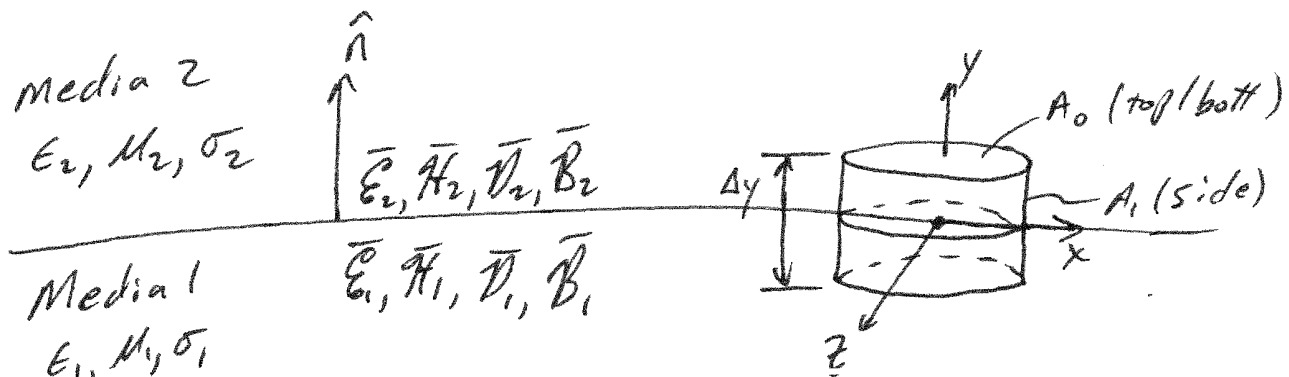
Since the x-components of \vec{H}_1 & \vec{H}_2 are tangential to the boundary, we get

$$\text{OR } \frac{H_{1t} = H_{2t}}{\hat{n} \times (\vec{H}_2 - \vec{H}_1) = 0} \quad \begin{array}{l} \sigma_1 + \sigma_2 \\ \text{finite} \end{array}$$

In words, the tangential magnetic field is continuous across the boundary between two finite conductivity media where there are no impressed electric current densities \vec{J}_i at the boundary.

\Rightarrow Tangential mag. flux density discontinuous $\frac{B_{1t}}{\mu_1} = \frac{B_{2t}}{\mu_2}$

1.5.1 cont.

Normal

Applying Gauss' Law w/ the assumption there are no charges at/on the boundary (reasonable w/ finite $\sigma_1 \neq \sigma_2$)

$$\oiint_S \vec{D} \cdot d\vec{s} = \iiint_V \rho_{\text{enc}} dV$$

$$\iint_{A_0} \vec{D}_2 \cdot d\vec{s}_y + \iint_{A_1 \text{ top}} \vec{D}_2 \cdot d\vec{s}_{\text{side}} + \iint_{A_1 \text{ bott}} \vec{D}_1 \cdot d\vec{s}_{\text{side}} + \iint_{A_0} \vec{D}_1 \cdot -d\vec{s}_y = 0$$

letting $\Delta y \rightarrow 0 \Rightarrow A_1 \rightarrow 0$

$$\vec{D}_2 \cdot \hat{a}_y A_0 + 0 + 0 - \vec{D}_1 \cdot \hat{a}_y A_0 = 0$$

Noting that the y -direction is NORMAL to boundary the boundary, we get:

$$\text{OR } \frac{D_{1n} = D_{2n}}{\hat{n} \cdot (\vec{D}_2 - \vec{D}_1) = 0} \quad \sigma_1 \neq \sigma_2 \text{ finite}$$

1.5.1 cont.

In words, the normal components of the electric flux density vector are continuous across the boundary of finite conductivity media w/out sources (charges)

If put in terms of the electric field

$$D_{1n} = \epsilon_1 E_{1n} = \epsilon_2 E_{2n} = \mathcal{V}_{2n} \quad \left(\begin{array}{l} \text{neglect} \\ \text{convolution} \end{array} \right)$$

$$\text{OR} \quad \hat{n} \cdot (\epsilon_2 \bar{E}_{2n} - \epsilon_1 \bar{E}_{1n}) = 0 \quad \begin{array}{l} \sigma_1 \neq \sigma_2 \\ \text{finite} \end{array}$$

\Rightarrow Normal components of electric field are discontinuous.

Next, use our last Maxwell Eq'n w/ the assumption that there are no magnetic charges on boundary

$$\oint_S \bar{B} \cdot d\bar{S} = \iiint_V \rho(\text{mr}) dv$$

to get $\underline{B_{1n} = B_{2n}}$

OR $\underline{\hat{n} \cdot (\bar{B}_2 - \bar{B}_1) = 0}$

1.5.1 cont.

In words, the normal component of the magnetic flux density vector is continuous across a boundary w/ no sources (charges)

If put in terms of the magnetic field

$$B_{1n} = \mu_1 H_{1n} = \mu_2 H_{2n} = B_{2n} \quad (\text{neglect convection})$$

or

$$\hat{n} \cdot (\mu_2 \vec{H}_2 - \mu_1 \vec{H}_1) = 0$$

⇒ Normal components of magnetic field are discontinuous.

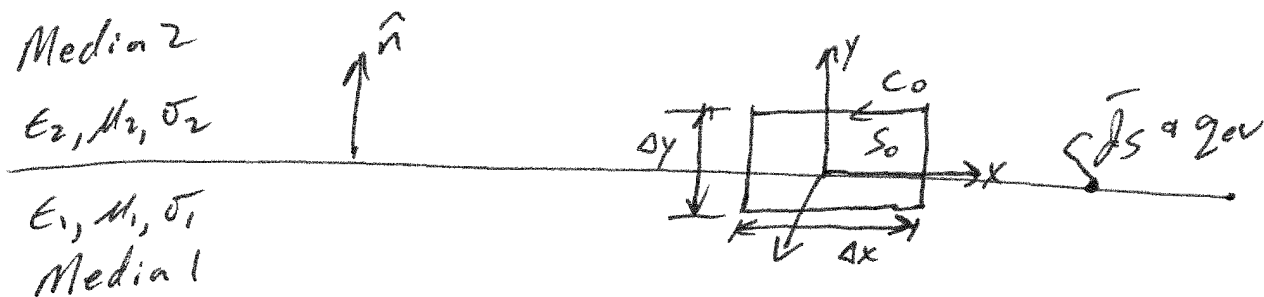
1.5.2 Infinite Conductivity Media

What occurs if there are electric sources and/or charges at the boundary, or if either of the media is a perfect electric conductor (PEC)? \Rightarrow Must include / allow for

surface current density \bar{J}_s (A/m)

\Rightarrow Must allow for surface electric charge density q_{ev} (C/m²)

Tangential



The application of Faraday's Law is unchanged by allowing \bar{J}_s &/or q_{ev} on boundary.

$$\bar{E}_{0it} = \bar{E}_{0rt} \Rightarrow \frac{V_{it}}{L_1} = \frac{V_{rt}}{L_2}$$

OR

$$\underline{\hat{n} \times (\bar{E}_2 - \bar{E}_1) = 0}$$

However, the application of Ampere's Law does change

$$\oint_{S_0} \bar{H} \cdot d\bar{l} = \iint_{S_0} \bar{J}_i \cdot d\bar{S} + \iint_S \bar{J}_c \cdot d\bar{S} + \frac{d}{dt} \iint_{S_0} \bar{D} \cdot d\bar{S}$$

Again, let $\Delta y \rightarrow 0 \Rightarrow S_0 \rightarrow 0$

1.5.2 cont.

$$\begin{aligned} (\bar{\mathcal{H}}_1 - \bar{\mathcal{H}}_2) \cdot \hat{a}_x \Delta x &= \lim_{\Delta y \rightarrow 0} [\bar{\mathcal{J}}_i \cdot \hat{a}_z \Delta x \Delta y] + 0 + 0 \\ &= \bar{\mathcal{J}}_s \cdot \hat{a}_z \Delta x \end{aligned} \quad \begin{array}{l} \downarrow \text{only surface} \\ \text{current density} \end{array}$$

dividing by Δx + re-arranging

$$(\bar{\mathcal{H}}_1 - \bar{\mathcal{H}}_2) \cdot \hat{a}_x - \bar{\mathcal{J}}_s \cdot \hat{a}_z = 0$$

$$\text{Note: } \hat{a}_x = \hat{a}_y \times \hat{a}_z$$

$$(\bar{\mathcal{H}}_1 - \bar{\mathcal{H}}_2) \cdot (\hat{a}_y \times \hat{a}_z) - \bar{\mathcal{J}}_s \cdot \hat{a}_z = 0$$

Use vector identity $\bar{A} \cdot (\bar{B} \times \bar{C}) = \bar{C} \cdot (\bar{A} \times \bar{B})$

on LHS, to get

$$\hat{a}_z \cdot [(\bar{\mathcal{H}}_1 - \bar{\mathcal{H}}_2) \times \hat{a}_y] - \hat{a}_z \cdot \bar{\mathcal{J}}_s = 0$$

$$\text{True IFF } (\bar{\mathcal{H}}_1 - \bar{\mathcal{H}}_2) \times \hat{a}_y - \bar{\mathcal{J}}_s = 0$$

$$(\bar{\mathcal{H}}_1 - \bar{\mathcal{H}}_2) \times \hat{a}_y = \bar{\mathcal{J}}_s$$

$$\text{Use } \bar{A} \times \bar{B} = -\bar{B} \times \bar{A}$$

$$\hat{a}_y \times (\bar{\mathcal{H}}_2 - \bar{\mathcal{H}}_1) = \bar{\mathcal{J}}_s$$

$$\text{Note: } \hat{a}_y = \hat{n}$$

$$\underline{\underline{\hat{n} \times (\bar{\mathcal{H}}_2 - \bar{\mathcal{H}}_1) = \bar{\mathcal{J}}_s}}$$

\Rightarrow Tangential magnetic field is discontinuous by an amount equal to the electric surface current density

1.5.2 cont.

What occurs to the tangential fields, if media 1 is a PEC (i.e., $\sigma_1 \rightarrow \infty$)?

$$\Rightarrow \bar{\mathcal{E}}_1 = 0 \Rightarrow \bar{\mathcal{V}}_1 = 0$$

This in turn causes

$$\mathcal{E}_{2t} = \mathcal{E}_{1t} \Big|_{\rightarrow 0} = 0 \Rightarrow \frac{\mathcal{V}_{2t}}{\epsilon_2} = 0 \Rightarrow \mathcal{V}_{2t} = 0$$

or

$$\underline{\hat{n} \times \bar{\mathcal{E}}_2 = 0} \quad \text{No tangential } \mathcal{E} \text{ next to PEC!}$$

In turn, from the differential form of Faraday's Law

$$\bar{\nabla} \times \bar{\mathcal{E}}_1 = 0 = -\nabla_{i1}^{\uparrow 0} - \frac{\partial \bar{\mathcal{B}}_1}{\partial t} \Rightarrow \bar{\mathcal{B}}_1 = 0$$

$$\text{(assumes } \mu_1 \text{ finite)} \Rightarrow \bar{\mathcal{H}}_1 = 0$$

Now, for $\sigma_1 \rightarrow \infty$,

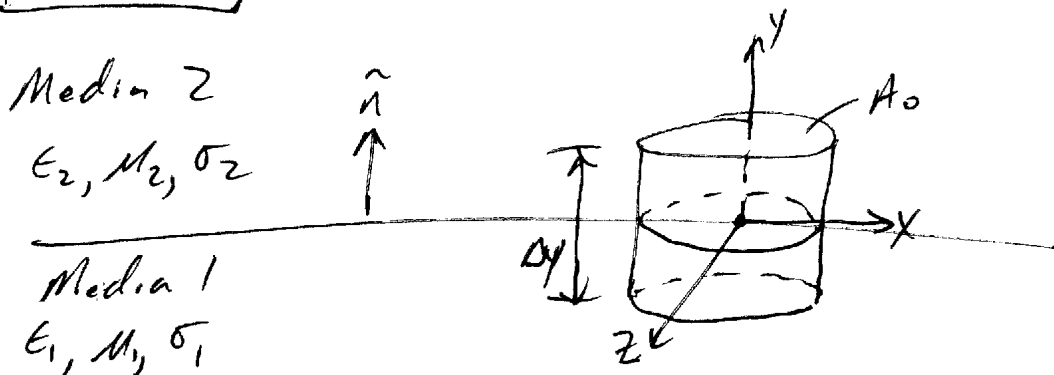
$$\hat{n} \times (\bar{\mathcal{H}}_2 - \bar{\mathcal{H}}_1) \Big|_{\rightarrow 0} = \bar{\mathcal{J}}_s$$

becomes

$$\underline{\hat{n} \times \bar{\mathcal{H}}_2 = \bar{\mathcal{J}}_s \Rightarrow |\bar{\mathcal{H}}_{2t}| = \mathcal{H}_{2t} = \mathcal{J}_s = |\bar{\mathcal{J}}_s|}$$

\Rightarrow Tangential \mathcal{H} is discontinuous next to a PEC by an amount equal to induced electric surface current density.

1.5.2 cont.

Normal

The application of Gauss' Law is changed by the possibility of a surface charge density q_{es}

$$\oiint_S \vec{D} \cdot d\vec{S} = \iiint_V q_{es} dv$$

Now, as $\Delta y \rightarrow 0$, we get

$$(\vec{D}_2 - \vec{D}_1) \cdot \hat{a}_y A_0 = q_{es} A_0$$

$$\Rightarrow \hat{n} = \hat{a}_y \Rightarrow \underline{\hat{n} \cdot (\vec{D}_2 - \vec{D}_1) = q_{es}}$$

$$\text{or } \underline{D_{2n} - D_{1n} = q_{es}}$$

$$\text{or } \underline{\hat{n} \cdot (\epsilon_2 \vec{E}_2 - \epsilon_1 \vec{E}_1) = q_{es}}$$

Both electric flux + electric field vectors are discontinuous across boundary w/ q_{es} .

1.5.2 cont.

The application of our last Maxwell eq'n is unchanged by q_{es}

$$\oint_S \vec{B} \cdot d\vec{s} = \iiint_V q_{mv} dv$$

⇓

$$\underline{B_{1n} = B_{2n}} \quad \text{or} \quad \underline{\hat{n} \cdot (\vec{B}_2 - \vec{B}_1) = 0}$$

$$\underline{\mu_1 H_{1n} = \mu_2 H_{2n}}$$

What happens to normal field components if media 1 is a PEC?

Per earlier, $\vec{E}_1 = \vec{D}_1 = \vec{B}_1 = \vec{H}_1 = 0$ (μ_1 finite).

Therefore,

$$\hat{n} \cdot \vec{D}_2 = q_{es} = D_{2n}$$

or

$$\hat{n} \cdot \vec{E}_2 = \frac{q_{es}}{\epsilon_2} = E_{2n}$$

and

$$\underline{B_{2n} = H_{2n} = 0}$$

⇒ The normal components of the electric field & flux are discontinuous next to a PEC.

1.5.3 Sources Along Boundaries

If we allow for \bar{M}_s (A/m) or \bar{J}_s (A/m), the magnetic & electric surface current densities, or for q_{ms} ($\frac{Wb}{m^2}$) or q_{es} (C/m^2), the magnetic & electric surface charge densities, the boundary conditions are:

$$\left. \begin{aligned} -\hat{n} \times (\bar{E}_2 - \bar{E}_1) &= \bar{M}_s \\ \hat{n} \times (\bar{H}_2 - \bar{H}_1) &= \bar{J}_s \end{aligned} \right\} \text{Tangential}$$

$$\left. \begin{aligned} \hat{n} \cdot (\bar{D}_2 - \bar{D}_1) &= q_{es} \\ \hat{n} \cdot (\bar{B}_2 - \bar{B}_1) &= q_{ms} \end{aligned} \right\} \text{Normal}$$

when media 1 and media 2 are NOT perfect conductors.

TABLE 1-3 Boundary conditions on instantaneous electromagnetic fields

		Finite conductivity media, no sources or charges $\sigma_1, \sigma_2 \neq \infty$ $\bar{J}_s = 0; q_{es} = 0$ $\bar{M}_s = 0; q_{ms} = 0$	Medium 1 of infinite electric conductivity $(\bar{E}_1 = \bar{H}_1 = 0)$ $\sigma_1 = \infty; \sigma_2 \neq \infty$ $\bar{M}_s = 0; q_{ms} = 0$	Medium 1 of infinite magnetic conductivity $(\bar{E}_1 = \bar{H}_1 = 0)$ $\bar{J}_s = 0; q_{es} = 0$
General				
Tangential electric field intensity	$-\hat{n} \times (\bar{E}_2 - \bar{E}_1) = \bar{M}_s$	$\hat{n} \times (\bar{E}_2 - \bar{E}_1) = 0$	$\hat{n} \times \bar{E}_2 = 0$	$-\hat{n} \times \bar{E}_2 = \bar{M}_s$
Tangential magnetic field intensity	$\hat{n} \times (\bar{H}_2 - \bar{H}_1) = \bar{J}_s$	$\hat{n} \times (\bar{H}_2 - \bar{H}_1) = 0$	$\hat{n} \times \bar{H}_2 = \bar{J}_s$	$\hat{n} \times \bar{H}_2 = 0$
Normal electric flux density	$\hat{n} \cdot (\bar{D}_2 - \bar{D}_1) = q_{es}$	$\hat{n} \cdot (\bar{D}_2 - \bar{D}_1) = 0$	$\hat{n} \cdot \bar{D}_2 = q_{es}$	$\hat{n} \cdot \bar{D}_2 = 0$
Normal magnetic flux density	$\hat{n} \cdot (\bar{B}_2 - \bar{B}_1) = q_{ms}$	$\hat{n} \cdot (\bar{B}_2 - \bar{B}_1) = 0$	$\hat{n} \cdot \bar{B}_2 = 0$	$\hat{n} \cdot \bar{B}_2 = q_{ms}$

1.5.3 cont.

Note: Perfect Magnetic Conductors (PMC) are also added.

PMCs do NOT physically exist, but can be used to simplify some EM problems

$$\text{PMCs: } \vec{E}_i = \vec{H}_i = 0, \quad \underline{\underline{\vec{J}_s}} = 0, \quad q_{es} = 0$$

(media 1)

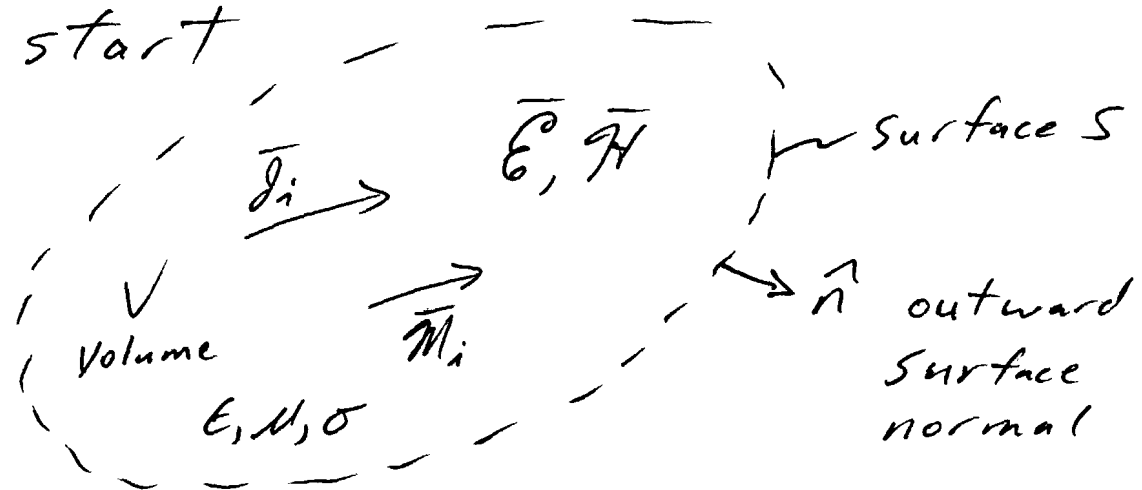
but can have $\vec{M}_s + q_{ms}$

1.6 Power and Energy

⇒ Pay homage to John Henry Poynting
(British physicist) and his 1884 paper

"On the Transfer of Energy in the
Electromagnetic Field"

To start



Faraday's $\vec{\nabla} \times \vec{E} = -\vec{\mathcal{M}}_i - \frac{\partial \vec{B}}{\partial t} = -\vec{\mathcal{M}}_i - \vec{\mathcal{M}}_d$

+
Ampere's $\vec{\nabla} \times \vec{H} = \vec{J}_i + \vec{J}_c + \frac{\partial \vec{D}}{\partial t} = \vec{J}_i + \vec{J}_c + \vec{J}_d$
Laws

Take dot product of \vec{H} w/ Faraday's and
 \vec{E} w/ Ampere's Law

$$\vec{H} \cdot (\vec{\nabla} \times \vec{E}) = -\vec{H} \cdot (\vec{\mathcal{M}}_i + \vec{\mathcal{M}}_d)$$

$$\vec{E} \cdot (\vec{\nabla} \times \vec{H}) = \vec{E} \cdot (\vec{J}_i + \vec{J}_c + \vec{J}_d)$$

Then, subtract the second eq'n from first

$$\vec{H} \cdot (\vec{\nabla} \times \vec{E}) - \vec{E} \cdot (\vec{\nabla} \times \vec{H}) = -\vec{H} \cdot (\vec{\mathcal{M}}_i + \vec{\mathcal{M}}_d) - \vec{E} \cdot (\vec{J}_i + \vec{J}_c + \vec{J}_d)$$

1.6 cont.

use vector identity $\nabla \cdot (\bar{A} \times \bar{B}) = \bar{B} \cdot (\nabla \times \bar{A}) - \bar{A} \cdot (\nabla \times \bar{B})$
to get

$$\nabla \cdot (\bar{E} \times \bar{H}) = -\bar{H} \cdot (\bar{M}_i + \bar{M}_d) - \bar{E} \cdot (\bar{J}_i + \bar{J}_c + \bar{J}_d)$$

$$\boxed{\nabla \cdot (\bar{E} \times \bar{H}) + \bar{H} \cdot (\bar{M}_i + \bar{M}_d) + \bar{E} \cdot (\bar{J}_i + \bar{J}_c + \bar{J}_d) = 0}$$

\Rightarrow differential form of Poynting Theorem

To get integral form, integrate over vol. V

$$\iiint_V \nabla \cdot (\bar{E} \times \bar{H}) dV + \iiint_V [\bar{H} \cdot (\bar{M}_i + \bar{M}_d) + \bar{E} \cdot (\bar{J}_i + \bar{J}_c + \bar{J}_d)] dV = 0$$

\downarrow
use divergence theorem

$$\boxed{\oiint_S (\bar{E} \times \bar{H}) \cdot d\bar{s} + \iiint_V [\bar{H} \cdot (\bar{M}_i + \bar{M}_d) + \bar{E} \cdot (\bar{J}_i + \bar{J}_c + \bar{J}_d)] dV = 0}$$

\Rightarrow integral form of Poynting Theorem

\Rightarrow Both deal w/ conservation of energy

Definitions & interpretations -

Poynting vector $\equiv \bar{S} = \bar{E} \times \bar{H}$ (W/m^2) Power density

$P_e = \oiint_S (\bar{E} \times \bar{H}) \cdot d\bar{s} = \oiint_S \bar{S} \cdot d\bar{s}$ is the power

leaving volume V through surface S

(in the EM field).

1.6 cont.

Supplied power density $\equiv \mathcal{P}_s = -(\bar{\mathcal{H}} \cdot \bar{\mathcal{M}}_i + \bar{\mathcal{E}} \cdot \bar{\mathcal{J}}_i) \quad (\text{W/m}^3)$

dissipated power density $\equiv \mathcal{P}_d = \bar{\mathcal{E}} \cdot \bar{\mathcal{J}}_c = \bar{\mathcal{E}} \cdot \sigma \bar{\mathcal{E}} = \sigma \mathcal{E}^2 \quad (\text{W/m}^3)$

The term $\bar{\mathcal{H}} \cdot \bar{\mathcal{M}}_i$ has to do w/ the time rate of change in the magnetic energy density w_m

$$\bar{\mathcal{H}} \cdot \bar{\mathcal{M}}_i = \bar{\mathcal{H}} \cdot \frac{d\bar{\mathcal{B}}}{dt} = \mu \bar{\mathcal{H}} \cdot \frac{d\bar{\mathcal{H}}}{dt} = \frac{1}{2} \mu \frac{d\mathcal{H}^2}{dt} = \frac{d}{dt} \left(\frac{1}{2} \mu \mathcal{H}^2 \right) \quad (\text{W/m}^3)$$

$$\text{where } w_m = \frac{1}{2} \mu \mathcal{H}^2 \quad (\text{J/m}^3)$$

The term $\bar{\mathcal{E}} \cdot \bar{\mathcal{J}}_d$ has to do w/ the time rate of change in the electric energy density w_e

$$\bar{\mathcal{E}} \cdot \bar{\mathcal{J}}_d = \bar{\mathcal{E}} \cdot \frac{d\bar{\mathcal{D}}}{dt} = \epsilon \bar{\mathcal{E}} \cdot \frac{d\bar{\mathcal{E}}}{dt} = \frac{1}{2} \epsilon \frac{d\mathcal{E}^2}{dt} = \frac{d}{dt} \left(\frac{1}{2} \epsilon \mathcal{E}^2 \right) \quad (\text{W/m}^3)$$

$$\text{where } w_e = \frac{1}{2} \epsilon \mathcal{E}^2 \quad (\text{J/m}^3)$$

Now, looking at the volume integral of these terms

$$\text{Supplied power} \equiv \mathcal{P}_s = -\iiint_V (\bar{\mathcal{H}} \cdot \bar{\mathcal{M}}_i + \bar{\mathcal{E}} \cdot \bar{\mathcal{J}}_i) dV = \iiint_V \mathcal{P}_s dV \quad (\text{W})$$

1.6 cont.

$$\text{dissipated power} \equiv P_d = \iiint_V (\bar{E} \cdot \bar{J}_c) dV = \iiint_V \sigma E^2 dV = \iiint_V P_d dV \text{ (W)}$$

$$\text{Time rate of magnetic energy } \mathcal{W}_m \text{ (J)} \equiv \iiint_V (\bar{H} \cdot \bar{M}_d) dV = \frac{d}{dt} \iiint_V \frac{1}{2} \mu H^2 dV$$

$$\text{stored w/in } V = \frac{d}{dt} \iiint_V w_m dV = \frac{d\mathcal{W}_m}{dt} \text{ (W)}$$

$$\text{Time rate of electric energy } \mathcal{W}_e \text{ (J)} \equiv \iiint_V (\bar{E} \cdot \bar{J}_d) dV = \frac{d}{dt} \iiint_V \frac{1}{2} \epsilon E^2 dV$$

$$\text{stored w/in } V = \frac{d}{dt} \iiint_V w_e dV = \frac{d\mathcal{W}_e}{dt} \text{ (W)}$$

w/ these definitions, we can re-write the integral form of the Poynting Theorem as

$$P_e - P_s + P_d + \frac{d}{dt}(\mathcal{W}_e + \mathcal{W}_m) = 0$$

OR

$$P_s = P_e + P_d + \frac{d}{dt}(\mathcal{W}_e + \mathcal{W}_m)$$

\uparrow \uparrow \uparrow \uparrow change in
 supplied leaving dissipated stored energy

which is why it is a conservation of power law (equation)!

1.7 Time-Harmonic Electromagnetic Fields

⇒ Many (most?) practical problems involve signals + EM waves that are time-harmonic, i.e., can be represented in terms of $\cos()$ or $\sin()$ functions (remember Fourier Series).

⇒ Here, the time-dependence can be represented by $e^{j\omega t}$ and we can express &/or analyze the EM fields in terms of their phasors.

⇒ Euler's Identity $e^{\pm jA} = \cos A \pm j \sin A$

$$\text{so, } \text{Re}\{V_0 e^{j\omega t}\} = V_0 \cos(\omega t)$$

We'll define for time-harmonic EM waves

$$\bar{\mathbf{E}}(x, y, z; t) = \text{Re}\left[\bar{\mathbf{E}}(x, y, z) e^{j\omega t}\right] \quad (\text{V/m})$$

$$\bar{\mathbf{H}}(x, y, z; t) = \text{Re}\left[\bar{\mathbf{H}}(x, y, z) e^{j\omega t}\right] \quad (\text{A/m})$$

$$\bar{\mathbf{D}}(x, y, z; t) = \text{Re}\left[\bar{\mathbf{D}}(x, y, z) e^{j\omega t}\right] \quad (\text{C/m}^2)$$

$$\bar{\mathbf{B}}(x, y, z; t) = \text{Re}\left[\bar{\mathbf{B}}(x, y, z) e^{j\omega t}\right] \quad (\text{wb/m}^2)$$

$$\bar{\mathbf{J}}(x, y, z; t) = \text{Re}\left[\bar{\mathbf{J}}(x, y, z) e^{j\omega t}\right] \quad (\text{A/m}^2)$$

$$\bar{q}(x, y, z; t) = \text{Re}\left[\bar{q}(x, y, z) e^{j\omega t}\right] \quad (\text{C})$$

↑
Instantaneous
(time-domain)

↑
complex spatial forms
(i.e., phasors)

←
peak values
(NOT RMS)

1.7.1 Maxwell's Equations in Differential and Integral Forms

- ⇒ Replace time-domain fields w/ phasors
- ⇒ $\frac{\partial \bar{\mathcal{N}}}{\partial t} \Rightarrow j\omega \bar{\mathcal{N}}$ since $\frac{\partial (\bar{\mathcal{N}} e^{j\omega t})}{\partial t} = \bar{\mathcal{N}} j\omega e^{j\omega t}$
and we divide out the $e^{j\omega t}$ terms
- ⇒ Easier to do EM problem solutions w/ phasors and then convert back to time-domain (if necessary)
- ⇒ Also, $\hat{\sigma} * \bar{\mathcal{E}} \Rightarrow \sigma \bar{\mathcal{E}}$! Constitutive eq's easier

TABLE 1-4 Instantaneous and time-harmonic forms of Maxwell's equations and continuity equation in differential and integral forms

Instantaneous	Time harmonic
Differential form	
$\nabla \times \mathcal{E} = -\mathcal{M}_i - \frac{\partial \mathcal{B}}{\partial t}$	$\nabla \times \mathbf{E} = -\mathbf{M}_i - j\omega \mathbf{B}$
$\nabla \times \mathcal{H} = \mathcal{J}_i + \mathcal{J}_c + \frac{\partial \mathcal{D}}{\partial t}$	$\nabla \times \mathbf{H} = \mathbf{J}_i + \mathbf{J}_c + j\omega \mathbf{D}$
$\nabla \cdot \mathcal{D} = q_{ev}$	$\nabla \cdot \mathbf{D} = q_{ev}$
$\nabla \cdot \mathcal{B} = q_{mv}$	$\nabla \cdot \mathbf{B} = q_{mv}$
$\nabla \cdot \mathcal{J}_{ic} = -\frac{\partial q_{ev}}{\partial t}$	$\nabla \cdot \mathbf{J}_{ic} = -j\omega q_{ev}$
Integral form	
$\oint_C \mathcal{E} \cdot d\ell = -\iint_S \mathcal{M}_i \cdot ds - \frac{\partial}{\partial t} \iint_S \mathcal{B} \cdot ds$	$\oint_C \mathbf{E} \cdot d\ell = -\iint_S \mathbf{M}_i \cdot ds - j\omega \iint_S \mathbf{B} \cdot ds$
$\oint_C \mathcal{H} \cdot d\ell = \iint_S \mathcal{J}_i \cdot ds + \iint_S \mathcal{J}_c \cdot ds + \frac{\partial}{\partial t} \iint_S \mathcal{D} \cdot ds$	$\oint_C \mathbf{H} \cdot d\ell = \iint_S \mathbf{J}_i \cdot ds + \iint_S \mathbf{J}_c \cdot ds + j\omega \iint_S \mathbf{D} \cdot ds$
$\iint_S \mathcal{D} \cdot ds = \mathcal{Q}_e$	$\iint_S \mathbf{D} \cdot ds = Q_e$
$\iint_S \mathcal{B} \cdot ds = \mathcal{Q}_m$	$\iint_S \mathbf{B} \cdot ds = Q_m$
$\iint_S \mathcal{J}_{ic} \cdot ds = -\frac{\partial \mathcal{Q}_e}{\partial t}$	$\iint_S \mathbf{J}_{ic} \cdot ds = -j\omega Q_e$

1.7.2 Boundary Conditions

⇒ In a similar fashion, we can update our derived boundary conditions for the time-harmonic case.

TABLE 1-5 Boundary conditions on time-harmonic electromagnetic fields

	General	Finite conductivity media, no sources or charges $\sigma_1, \sigma_2 \neq \infty$ $\mathbf{J}_s = \mathbf{M}_s = \mathbf{0}$ $q_{es} = q_{ms} = 0$	Medium 1 of infinite electric conductivity $(\mathbf{E}_1 = \mathbf{H}_1 = \mathbf{0})$ $\sigma_1 = \infty; \sigma_2 \neq \infty$ $\mathbf{M}_s = \mathbf{0}; q_{ms} = 0$	Medium 1 of infinite magnetic conductivity $(\mathbf{E}_1 = \mathbf{H}_1 = \mathbf{0})$ $\mathbf{J}_s = \mathbf{0}; q_{es} = 0$
Tangential electric field intensity	$-\hat{\mathbf{n}} \times (\mathbf{E}_2 - \mathbf{E}_1) = \mathbf{M}_s$	$\hat{\mathbf{n}} \times (\mathbf{E}_2 - \mathbf{E}_1) = 0$	$\hat{\mathbf{n}} \times \mathbf{E}_2 = 0$	$-\hat{\mathbf{n}} \times \mathbf{E}_2 = \mathbf{M}_s$
Tangential magnetic field intensity	$\hat{\mathbf{n}} \times (\mathbf{H}_2 - \mathbf{H}_1) = \mathbf{J}_s$	$\hat{\mathbf{n}} \times (\mathbf{H}_2 - \mathbf{H}_1) = 0$	$\hat{\mathbf{n}} \times \mathbf{H}_2 = \mathbf{J}_s$	$\hat{\mathbf{n}} \times \mathbf{H}_2 = 0$
Normal electric flux density	$\hat{\mathbf{n}} \cdot (\mathbf{D}_2 - \mathbf{D}_1) = q_{es}$	$\hat{\mathbf{n}} \cdot (\mathbf{D}_2 - \mathbf{D}_1) = 0$	$\hat{\mathbf{n}} \cdot \mathbf{D}_2 = q_{es}$	$\hat{\mathbf{n}} \cdot \mathbf{D}_2 = 0$
Normal magnetic flux density	$\hat{\mathbf{n}} \cdot (\mathbf{B}_2 - \mathbf{B}_1) = q_{ms}$	$\hat{\mathbf{n}} \cdot (\mathbf{B}_2 - \mathbf{B}_1) = 0$	$\hat{\mathbf{n}} \cdot \mathbf{B}_2 = 0$	$\hat{\mathbf{n}} \cdot \mathbf{B}_2 = q_{ms}$

Advanced Engineering Electromagnetics (Second Edition), Balanis, Wiley, 2012, ISBN-10: 0470589485, ISBN-13: 978-0470589489.

What if media 1 is a very good conductor, but NOT a PEC?

Now, the surface current is approximately related to the tangential magnetic field

$$\underline{\underline{\mathbf{J}_s = \hat{\mathbf{n}} \times \mathbf{H}_2}}$$

⇒ reality is that current density drops exponentially from surface into media 1 (skin effect)

1.7.2 cont.

Looking ahead to chap 4, define surface impedance of media 1 as

$$Z_s = R_s + jX_s = (1+j) \sqrt{\frac{\omega \mu_1}{2\sigma_1}}$$

Now, the tangential electric field in media 2 is NOT zero (will be small)

$$\underline{\bar{E}_{t2} = Z_s \bar{J}_s = Z_s \hat{n} \times \bar{H}_2}$$

Now, we must consider what happens to the normal components. As it turns out, they are dependent on the tangential field components in this case.

Use Faraday's & Ampere's equations w/ tangential \bar{E} (Faraday) and \bar{H} (Ampere) on LHS

$$\bar{\nabla} \times \bar{E} = -\bar{\nabla} \cdot \bar{A} - j\omega \bar{B} = -j\omega \mu \bar{H}$$

$$\bar{\nabla} \times \bar{H} = \bar{J}_A + \bar{J}_c + j\omega \bar{D}$$

1.7.3 Power and Energy

$$\text{Let/note } \bar{E} = \text{Re}[\bar{E} e^{j\omega t}] = \frac{1}{2} [\bar{E} e^{j\omega t} + (\bar{E} e^{j\omega t})^*]$$

$$\bar{H} = \text{Re}[\bar{H} e^{j\omega t}] = \frac{1}{2} [\bar{H} e^{j\omega t} + (\bar{H} e^{j\omega t})^*]$$

Then, the instantaneous Poynting vector is

$$\begin{aligned} \bar{S} &= \bar{E} \times \bar{H} = \frac{1}{2} [\bar{E} e^{j\omega t} + \bar{E}^* e^{-j\omega t}] \times \frac{1}{2} [\bar{H} e^{j\omega t} + \bar{H}^* e^{-j\omega t}] \\ &= \frac{1}{2} [\underbrace{\text{Re}(\bar{E} \times \bar{H}^*)}_{\substack{\uparrow \\ \text{constant wrt } t}} + \underbrace{\text{Re}(\bar{E} \times \bar{H} e^{j2\omega t})}_{\substack{\uparrow \\ \text{varies @ freq } 2\omega}}] \quad (\text{W/m}^2) \end{aligned}$$

$$\bar{S}_{\text{ave}} = \frac{1}{T} \int_{t_0}^{t_0+T} \bar{S} dt = \underline{\bar{S}_{\text{ave}}} = \frac{1}{2} \text{Re}(\bar{E} \times \bar{H}^*) \equiv \begin{matrix} \text{Time-ave} \\ \text{Poynting} \\ \text{vector} \end{matrix}$$

Note: The imaginary part of $\bar{E} \times \bar{H}^*$ is related to reactive power.

To derive the Poynting Theorem for the time-harmonic form, dot \bar{H}^* w/ Faraday's Law and \bar{E} w/ Ampere's Law complex conjugate

$$\bar{H}^* \cdot (\nabla \times \bar{E}) = -\bar{H}^* \cdot \bar{M}_i - j\omega M \bar{H} \cdot \bar{H}^* \rightarrow |\bar{H}|^2$$

$$\bar{E} \cdot (\nabla \times \bar{H}^*) = \bar{E} \cdot \bar{J}_i^* + \sigma \bar{E} \cdot \bar{E}^* \rightarrow |\bar{E}|^2 - j\omega \epsilon \bar{E} \cdot \bar{E}^* \rightarrow |\bar{E}|^2$$

1.7.3 cont.

Next subtract the second eq'n from the first

and apply $\nabla \cdot (\bar{A} \times \bar{B}) = \bar{B} \cdot (\nabla \times \bar{A}) - \bar{A} \cdot (\nabla \times \bar{B})$

$$\nabla \cdot (\bar{H}^* \times \bar{E}) = -\nabla \cdot (\bar{E} \times \bar{H}^*) = \bar{H}^* \cdot \bar{M}_i + \bar{E} \cdot \bar{J}_i^* + \sigma |\bar{E}|^2 + j\omega [\mu |\bar{H}|^2 - \epsilon |\bar{E}|^2]$$

Divide by 2 to get (W/m³)

$$-\nabla \cdot (\frac{1}{2} \bar{E} \times \bar{H}^*) = \frac{1}{2} \bar{H}^* \cdot \bar{M}_i + \frac{1}{2} \bar{E} \cdot \bar{J}_i^* + \frac{1}{2} \sigma |\bar{E}|^2 + j2\omega \left[\frac{\mu}{4} |\bar{H}|^2 - \frac{\epsilon}{4} |\bar{E}|^2 \right]$$

Poynting theorem in differential form for time-harmonic case.

To get integral form, again integrate over volume V & use divergence theorem and some algebra

$$\begin{aligned} -\frac{1}{2} \iiint_V (\bar{H}^* \cdot \bar{M}_i + \bar{E} \cdot \bar{J}_i^*) dV &= \oint_S (\frac{1}{2} \bar{E} \times \bar{H}^*) \cdot d\bar{S} \\ &+ \frac{1}{2} \iiint_V \sigma |\bar{E}|^2 dV \quad (\text{W}) \\ &+ j2\omega \iiint_V \left[\frac{\mu}{4} |\bar{H}|^2 - \frac{\epsilon}{4} |\bar{E}|^2 \right] dV \end{aligned}$$

Here, we define -

$$\text{Supplied complex} \equiv P_S = -\frac{1}{2} \iiint_V (\bar{H}^* \cdot \bar{M}_i + \bar{E} \cdot \bar{J}_i^*) dV$$

power (W)

1.7.3 cont.

$$\text{Exiting complex} \equiv P_e = \iint_S (\frac{1}{2} \bar{E} \times \bar{H}^*) \cdot d\bar{S}$$

power (W)

$$\text{Dissipated real} \equiv P_d = \frac{1}{2} \iiint_V \sigma |\bar{E}|^2 dV$$

power (W)

$$\text{Time-ave magnetic} \equiv \bar{W}_m = \iiint_V \frac{1}{4} \mu |\bar{H}|^2 dV$$

energy (J)

$$\text{Time-ave electric} \equiv \bar{W}_e = \iiint_V \frac{1}{4} \epsilon |\bar{E}|^2 dV$$

energy (J)

which leads to

$$\frac{P_S = P_e + P_d + j2\omega(\bar{W}_m - \bar{W}_e)}{\substack{\uparrow \quad \uparrow \quad \uparrow \\ \text{complex} \quad \text{real} \quad \text{reactive/imaginary}}}$$

Note: IF ϵ or μ are complex, the real portions of the last terms are combined w/ P_d as they'll be losses.

1.7.3 cont.

For the time-harmonic case, the relations between field quantities and circuit theory are given in Table 1-6.

TABLE 1-6 Relations between time-harmonic electromagnetic field and steady-state a.c. circuit theories

Field theory	Circuit theory
1. \mathbf{E} (electric field intensity)	1. v (voltage)
2. \mathbf{H} (magnetic field intensity)	2. i (current)
3. \mathbf{D} (electric flux density)	3. q_{ev} (electric charge density)
4. \mathbf{B} (magnetic flux density)	4. q_{mv} (magnetic charge density)
5. \mathbf{J} (electric current density)	5. i_e (electric current)
6. \mathbf{M} (magnetic current density)	6. i_m (magnetic current)
7. $\mathbf{J}_d = j\omega\epsilon\mathbf{E}$ (electric displacement current density)	7. $i = j\omega Cv$ (current through a capacitor)
8. $\mathbf{M}_d = j\omega\mu\mathbf{H}$ (magnetic displacement current density)	8. $v = j\omega Li$ (voltage across an inductor)
9. <i>Constitutive relations</i>	9. <i>Element laws</i>
(a) $\mathbf{J}_c = \sigma\mathbf{E}$ (electric conduction current density)	(a) $i = Gv = \frac{1}{R}v$ (Ohm's law)
(b) $\mathbf{D} = \epsilon\mathbf{E}$ (dielectric material)	(b) $Q_e = Cv$ (charge in a capacitor)
(c) $\mathbf{B} = \mu\mathbf{H}$ (magnetic material)	(c) $\psi = Li$ (flux of an inductor)
10. $\oint_C \mathbf{E} \cdot d\boldsymbol{\ell} = -j\omega \iint_S \mathbf{B} \cdot d\mathbf{s}$ (Maxwell-Faraday equation)	10. $\sum v = -j\omega L_s i \simeq 0$ (Kirchhoff's voltage law)
11. $\iint_S \mathbf{J}_{ic} \cdot d\mathbf{s} = -j\omega \iiint_V q_{ev} dv = -\frac{\partial Q_e}{\partial t}$ (continuity equation)	11. $\sum i = -j\omega Q_e = -j\omega C_s v \simeq 0$ (Kirchhoff's current law)
12. <i>Power and energy densities</i>	12. <i>Power and energy</i> (v and i represent peak values)
(a) $\frac{1}{2} \iint_S (\mathbf{E} \times \mathbf{H}^*) \cdot d\mathbf{s}$ (complex power)	(a) $P = \frac{1}{2} vi$ (power-voltage-current relation)
(b) $\frac{1}{2} \iiint_V \sigma \mathbf{E} ^2 dv$ (dissipated real power)	(b) $P_d = \frac{1}{2} G v^2 = \frac{1}{2} \frac{v^2}{R}$ (power dissipated in a resistor)
(c) $\frac{1}{4} \iiint_V \epsilon \mathbf{E} ^2 dv$ (time-average electric stored energy)	(c) $\frac{1}{4} C v^2$ (energy stored in a capacitor)
(d) $\frac{1}{4} \iiint_V \mu \mathbf{H} ^2 dv$ (time-average magnetic stored energy)	(d) $\frac{1}{4} L i^2$ (energy stored in an inductor)