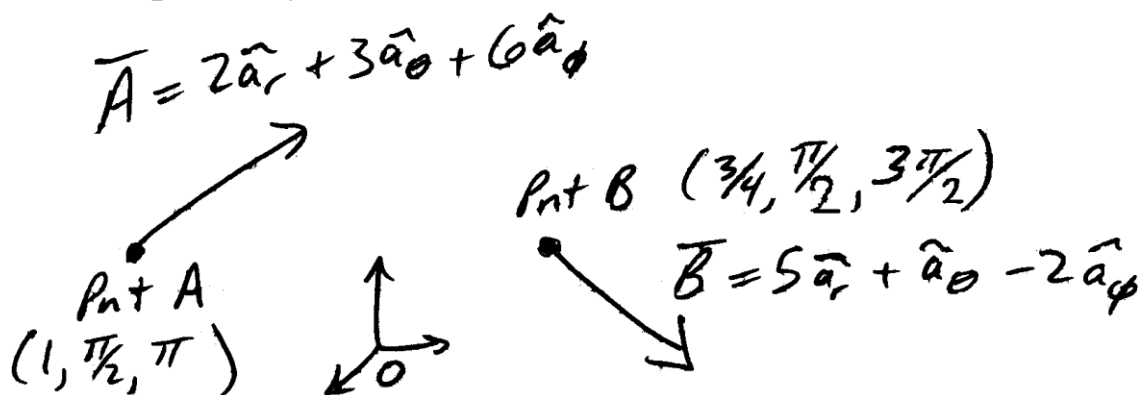


Example- Add the vectors $\bar{A} = 2\hat{a}_r + 3\hat{a}_\theta + 6\hat{a}_\phi$ and $\bar{B} = 5\hat{a}_r + \hat{a}_\theta - 2\hat{a}_\phi$ defined in spherical coordinates at the points $A(1, \pi/2, \pi)$ and $B(3/4, \pi/2, 3\pi/2)$, respectively.



when $\bar{A} + \bar{B}$ are NOT defined at the same point

$$\bar{A} + \bar{B} \neq (A_r + B_r)\hat{a}_r + (A_\theta + B_\theta)\hat{a}_\theta + (A_\phi + B_\phi)\hat{a}_\phi$$

$$\bar{A} + \bar{B} \neq (2+5)\hat{a}_r + (3+1)\hat{a}_\theta + (6-2)\hat{a}_\phi$$

$$\neq 7\hat{a}_r + 4\hat{a}_\theta + 4\hat{a}_\phi$$

since $\hat{a}_r, \hat{a}_\theta, \hat{a}_\phi$ point different directions at A & B

\Rightarrow easiest solution convert $\hat{a}_r, \hat{a}_\theta, \hat{a}_\phi$

to $\hat{a}_x, \hat{a}_y, \hat{a}_z$

OR

calculate A_x, A_y, A_z from A_r, A_θ, A_ϕ

then add $\bar{A} + \bar{B}$ together

ex. cont.

Method 1 (convert unit vectors)@ pt A (1, $\frac{\pi}{2}$, π)

$$\hat{a}_r = \sin^1 \frac{\pi}{2} \cos^{\pi-1} \hat{a}_x + \sin \frac{\pi}{2} \sin^{\pi} \hat{a}_y + \cos^1 \frac{\pi}{2} \hat{a}_z$$

$$\hat{a}_r = -\hat{a}_x$$

$$\hat{a}_\theta = \cos \frac{\pi}{2} \cos^{\pi} \hat{a}_x + \cos \frac{\pi}{2} \sin^{\pi} \hat{a}_y - \sin \frac{\pi}{2} \hat{a}_z$$

$$\hat{a}_\theta = -\hat{a}_z$$

$$\hat{a}_\phi = -\sin^{\pi} \hat{a}_x + \cos^{\pi-1} \hat{a}_y = -\hat{a}_y$$

So

$$\bar{A} = 2\hat{a}_r + 3\hat{a}_\theta + 6\hat{a}_\phi = -2\hat{a}_x - 3\hat{a}_z - 6\hat{a}_y$$

@ pt B (3/4, $\frac{\pi}{2}$, $3\frac{\pi}{2}$)

$$\hat{a}_r = \sin \frac{\pi}{2} \cos^{\frac{3\pi}{2}} \hat{a}_x + \sin \frac{\pi}{2} \sin^{\frac{3\pi}{2}} \hat{a}_y + \cos^1 \frac{\pi}{2} \hat{a}_z = -\hat{a}_y$$

$$\hat{a}_\theta = \cos \frac{\pi}{2} \cos^{\frac{3\pi}{2}} \hat{a}_x + \cos \frac{\pi}{2} \sin^{\frac{3\pi}{2}} \hat{a}_y - \sin \frac{\pi}{2} \hat{a}_z = -\hat{a}_z$$

$$\hat{a}_\phi = -\sin^{\frac{3\pi}{2}} \hat{a}_x + \cos^{\frac{3\pi}{2}} \hat{a}_y = \hat{a}_x$$

So

$$\bar{B} = 5\hat{a}_r + \hat{a}_\theta - 2\hat{a}_\phi = -5\hat{a}_y - \hat{a}_z - 2\hat{a}_x$$

$$\bar{A} + \bar{B} = (-2-2)\hat{a}_x + (-6-5)\hat{a}_y + (-3-1)\hat{a}_z$$

$$\bar{A} + \bar{B} = -4\hat{a}_x - 11\hat{a}_y - 4\hat{a}_z$$

EX. cont.

Method 2 (find A_x, A_y, A_z, \dots)

@ pt A ($r=1, \theta=\pi/2, \phi=\pi$)

$$A_x = 2 \sin \pi/2 \cos \pi + 3 \cos \pi/2 \cos \pi - 6 \sin \pi = -2$$

$$A_y = 2 \sin \pi/2 \sin \pi + 3 \cos \pi/2 \sin \pi + 6 \cos \pi = -6$$

$$A_z = 2 \cos \pi/2 - 3 \sin \pi/2 = -3$$

So $\bar{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z$

$$\bar{A} = -2\hat{a}_x - 6\hat{a}_y - 3\hat{a}_z$$

Similarly @ pt B ($r=3/4, \theta=\pi/2, \phi=3\pi/2$)

$$B_x = 5 \sin \pi/2 \cos 3\pi/2 + (1) \cos \pi/2 \cos 3\pi/2 - (-2) \sin 3\pi/2 = -2$$

$$B_y = 5 \sin \pi/2 \sin 3\pi/2 + (1) \cos \pi/2 \sin 3\pi/2 + (-2) \cos 3\pi/2 = -5$$

$$B_z = 5 \cos \pi/2 - (1) \sin \pi/2 = -1$$

So $\bar{B} = B_x \hat{a}_x + B_y \hat{a}_y + B_z \hat{a}_z$

$$\bar{B} = -2\hat{a}_x - 5\hat{a}_y - \hat{a}_z$$

and

$$\bar{A} + \bar{B} = (A_x + B_x) \hat{a}_x + (A_y + B_y) \hat{a}_y + (A_z + B_z) \hat{a}_z$$

$$\bar{A} + \bar{B} = -4\hat{a}_x - 11\hat{a}_y - 4\hat{a}_z \quad \therefore \text{Same!}$$