

7.4 Using the transform pairs in Table 7.3 and the properties of the  $z$ -transform in Table 7.2, determine the  $z$ -transform of the following discrete-time signals:

(b)  $x[n] = (\sin^2 \omega n)u[n]$

Use Trigonometric identity  $\sin^2 A = \frac{1}{2} - \frac{1}{2} \cos 2A$   
to get

$$X[n] = \frac{1}{2} u[n] - \frac{1}{2} \cos(2\omega n) u[n]$$

Now, use the linearity property and Table 7.3  
Transform pairs

$$u[n] \leftrightarrow \frac{z}{z-1}$$

$$(\cos \omega n) u[n] \leftrightarrow \frac{z^2 - (\cos \omega) z}{z^2 - (2 \cos \omega) z + 1}$$

to get

$$\underline{X(z) = \frac{0.5z}{z-1} - 0.5 \frac{z^2 - (\cos 2\omega) z}{z^2 - 2 \cos 2\omega z + 1}}$$

or

$$\underline{\underline{X(z) = \frac{0.5(1-\cos 2\omega)z^2 + 0.5(1-\cos 2\omega)z}{z^3 - (1+2\cos 2\omega)z^2 + (1+2\cos 2\omega)z - 1}}}$$

7.4 Using the transform pairs in Table 7.3 and the properties of the  $z$ -transform in Table 7.2, determine the  $z$ -transform of the following discrete-time signals:

(f)  $x[n] = ne^{-bn}(\sin \omega n)u[n]$

$$X[n] = n(e^{-b})^n \sin(\omega n) u[n]$$

Use Table 7.3 transform pair:

$$a^n \sin(\omega n) u[n] \leftrightarrow \frac{a \sin(\omega) z}{z^2 - 2a \cos(\omega) z + a^2}$$

and the Table 7.2 property

$$n x[n] \leftrightarrow -z \frac{d X(z)}{dz}$$

$$X(z) = -z \frac{d}{dz} \left[ \frac{e^{-b} \sin(\omega) z}{z^2 - 2e^{-b} \cos(\omega) z + e^{-2b}} \right]$$

$$= -z \left[ \frac{(z^2 - 2e^{-b} \cos(\omega) z + e^{-2b}) e^{-b} \sin(\omega) - e^{-b} \sin(\omega) z (2z - 2e^{-b} \cos(\omega))}{(z^2 - 2e^{-b} \cos(\omega) z + e^{-2b})^2} \right]$$

$$= -z \left[ \frac{(e^{-b} \sin(\omega) - 2e^{-b} \sin(\omega)) z^2 + (-2e^{-2b} \cos(\omega) \sin(\omega) + 2e^{-2b} \cos(\omega) \sin(\omega)) z + e^{-3b} \sin(\omega)}{(z^2 - 2e^{-b} \cos(\omega) z + e^{-2b})^2} \right]$$

$$X(z) = \frac{e^{-b} \sin(\omega) z^3 - e^{-3b} \sin(\omega) z}{(z^2 - 2e^{-b} \cos(\omega) z + e^{-2b})^2}$$

$$\underline{X(z) = \frac{e^{-b} \sin(\omega) z (z^2 - e^{-2b})}{(z^2 - 2e^{-b} \cos(\omega) z + e^{-2b})^2}}$$