

5.13 A linear time-invariant continuous-time system has the frequency function $H(\omega)$. It is known that the input

$$x(t) = 1 + 4 \cos 2\pi t + 8 \sin(3\pi t - 90^\circ)$$

produces the response

$$y(t) = 2 - 2 \sin 2\pi t$$

(a) For what values of ω is it possible to determine $H(\omega)$?

(b) Compute $H(\omega)$ for each of the values of ω determined in part (a).

a) $X(t) = 1 + 4 \cos 2\pi t + 8 \cos(3\pi t - 180^\circ)$ contains frequency components at $\omega = 0$ (DC), 2π (rad/s), & 3π (rad/s).

$y(t) = 2 + 2 \cos(2\pi t + 90^\circ)$ contains frequency components at $\omega = 0$ & 2π (rad/s) w/ nothing at $\omega = 3\pi$ (rad/s)

$$\text{Since } Y(\omega) = X(\omega)H(\omega) \Rightarrow H(\omega) = \frac{Y(\omega)}{X(\omega)}$$

\Rightarrow We can determine $H(\omega)$ at $\omega = 0, 2\pi, + 3\pi$ rad/s

b) use phasors

$$H(0) = \frac{Y(0)}{X(0)} = \frac{2}{1} = \underline{\underline{2}}$$

$$H(2\pi) = \frac{Y(2\pi)}{X(2\pi)} = \frac{2 \angle 90^\circ}{4 \angle 0^\circ} = \underline{\underline{0.5 \angle 90^\circ}} = 0.5 e^{j\pi/2} = j0.5$$

$$H(3\pi) = \frac{Y(3\pi)}{X(3\pi)} = \frac{0}{8 \angle -180^\circ} = \underline{\underline{0}}$$