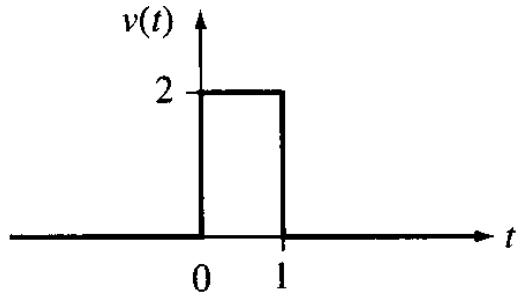
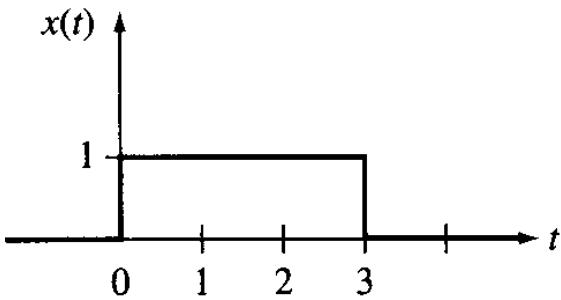


- 2.29** For the continuous-time signals $x(t)$ and $v(t)$ shown in Figure P2.29, compute the convolution $x(t) * v(t)$ for all $t \geq 0$, and plot your resulting signal.

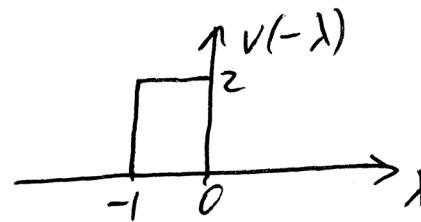
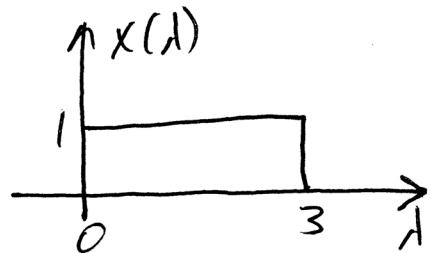


(a)

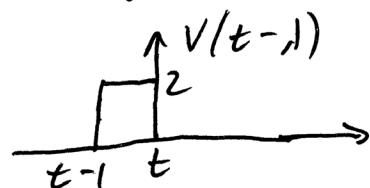
$$(2.72) \quad X(t) * V(t) = \int_{-\infty}^{\infty} x(\lambda) V(t-\lambda) d\lambda$$

$\downarrow \begin{matrix} \text{change} \\ t \rightarrow -\lambda \end{matrix}$

change $t \rightarrow \lambda$



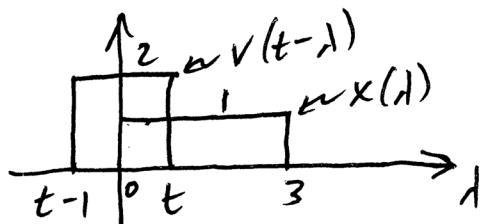
\downarrow time-shift



1st interval, $t \leq 0$ $x(\lambda) + v(t-\lambda)$ do NOT overlap

$$\Rightarrow \underline{x(t) * v(t) = 0, t \leq 0}$$

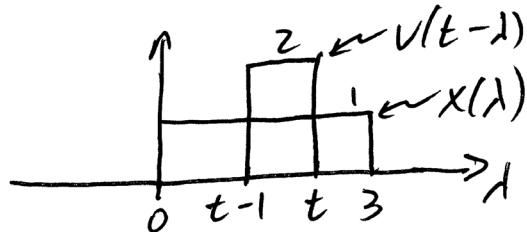
2nd interval $0 \leq t \leq 1$ leading edge of $v(t-\lambda)$ overlaps, trailing edge does NOT overlap



$$x(t) * v(t) = \int_0^t z(\lambda) d\lambda = zt \Big|_0^t = 2t - 0$$

$$\underline{x(t) * v(t) = 2t, \quad 0 \leq t \leq 1s}$$

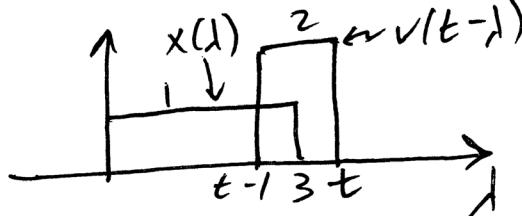
3rd interval, $1 \leq t \leq 3s$ Full overlap



$$\begin{aligned} x(t) * v(t) &= \int_{t-1}^t z(\lambda) d\lambda = zt \Big|_{t-1}^t \\ &= 2t - 2(t-1) \end{aligned}$$

$$\underline{x(t) * v(t) = 2, \quad 1 \leq t \leq 3s}$$

4th interval, $3 \leq t \leq 4s$ Trailing edge of $v(t-λ)$ overlaps



$$\begin{aligned} x(t) * v(t) &= \int_{t-1}^3 z(\lambda) d\lambda = zt \Big|_{t-1}^3 \\ &= 2(3) - 2(t-1) \end{aligned}$$

$$\underline{x(t) * v(t) = 8 - 2t, \quad 3 \leq t \leq 4s}$$

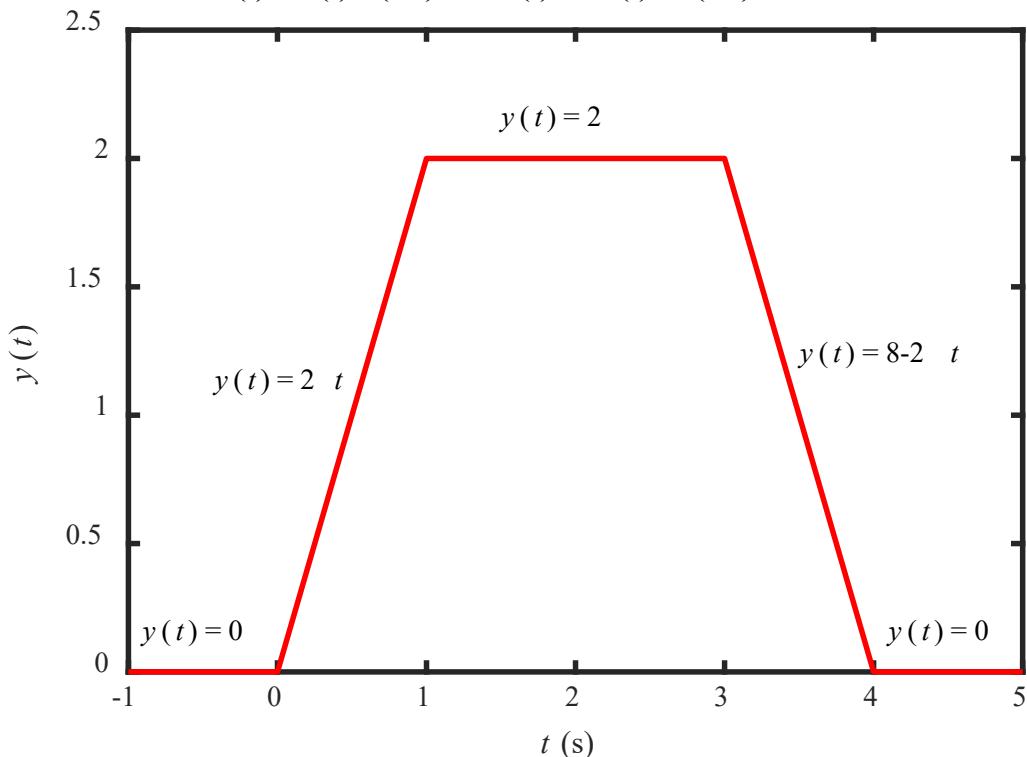
5th interval, $t > 4s$ No overlap

$$\underline{x(t) * v(t) = 0, \quad t > 4s}$$

```
% Chapter 2 problem 2.29a (p2_29a.m)
% Plot the convolution of
% x(t) = u(t)-u(t-3) with v(t) = 2u(t)-2u(t-1).
% The analytic result is
%     x(t)*v(t) = 2t for 0 < t < 1 s
%     x(t)*v(t) = 2 for 1 < t < 3 s
%     x(t)*v(t) = 8 - 2t for 3 < t < 4 s
%     x(t)*v(t) = 0 for all other t
clear; clc; close all;
% Calculate the analytic results
t0 = -1:0.1:0; t1 = 0:0.1:1; t2 = 1:0.1:3; t3 = 3:0.1:4; t4 = 4:0.1:5;
y0 = 0*t0; y1 = 2*t1; y2 = 2+0*t2; y3 = 8-2*t3; y4 = 0*t4;
t = [t0 t1 t2 t3 t4]; y = [y0 y1 y2 y3 y4]; % splice together
%
plot(t,y, 'r-'), axis([-1 5 0 2.5]),
ylabel('y(t)', 'fontsize', 16, 'fontname', 'times')
xlabel('t (s)', 'fontsize', 16, 'fontname', 'times')
title({'Problem 2.29a, y(t) = x(t)* v(t); ...',
'x(t) = u(t)-u(t-3) and v(t) = 2u(t)-2u(t-1)', ...
'fontsize', 18, 'fontname', 'times'})
text(-0.9, 0.12, 'y(t) = 0', 'fontsize', 14, 'fontname', 'times')
text(-0.42, 1.1, 'y(t) = 2t', 'fontsize', 14, 'fontname', 'times')
text(1.5, 2.12, 'y(t) = 2', 'fontsize', 14, 'fontname', 'times')
text(3.5, 1.2, 'y(t) = 8-2t', 'fontsize', 14, 'fontname', 'times')
text(4.1, 0.12, 'y(t) = 0', 'fontsize', 14, 'fontname', 'times')
set(findobj('type','line'), 'linewidth', 2, 'markersize', 12)
set(findobj('type','axes'), 'linewidth', 2, 'fontsize', 14, 'fontname', 'times')
```

Problem 2.29a, $y(t) = x(t)* v(t)$

$$x(t) = u(t)-u(t-3) \text{ and } v(t) = 2u(t)-2u(t-1)$$



- 2.29** For the continuous-time signals $x(t)$ and $v(t)$ shown in Figure P2.29, compute the convolution $x(t) * v(t)$ for all $t \geq 0$, and plot your resulting signal.

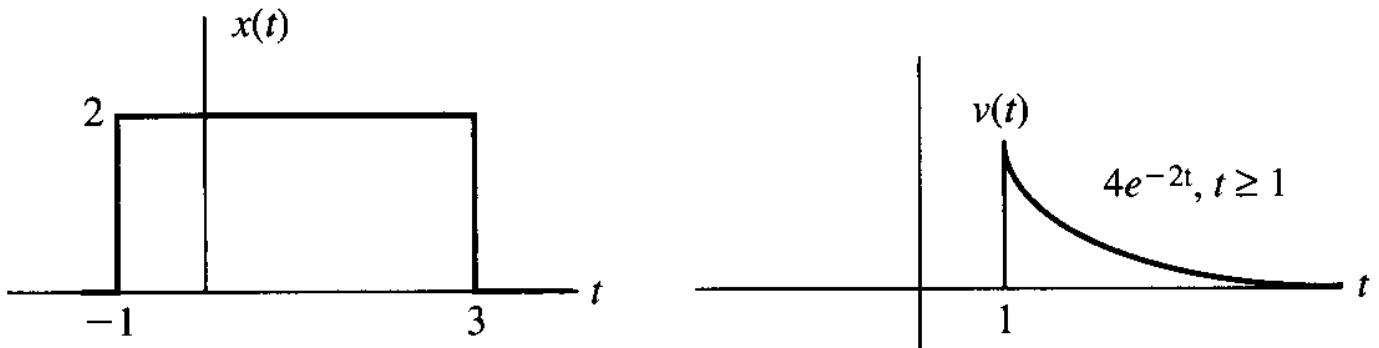
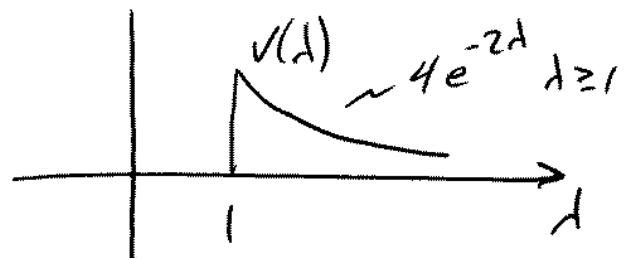
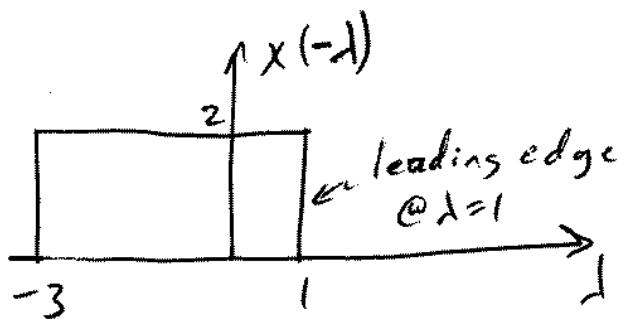
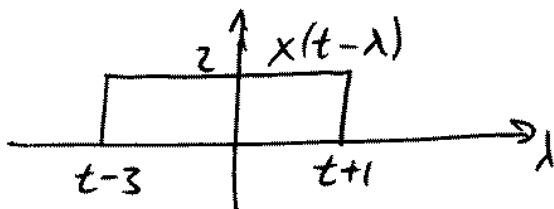


FIGURE P2.29 (e)

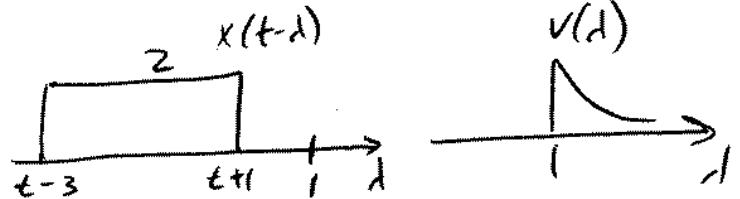
Using commutativity, $x(t) * v(t) = v(t) * x(t) = \int_{-\infty}^{\infty} v(\lambda) x(t-\lambda) d\lambda$



↓ Time-shift by t
 $-\lambda \rightarrow t-\lambda$



1st Interval ($t < 0$)

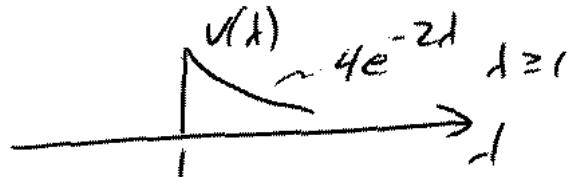
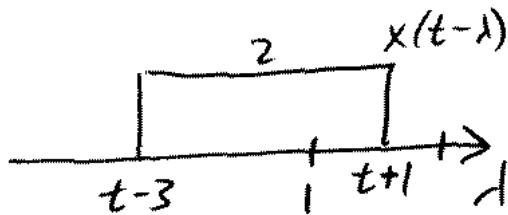


$\Rightarrow x(t-\lambda)$ and $v(\lambda)$ do not overlap

$$\underline{x(t) * v(t) = 0}$$

2nd Interval ($0 < t \leq 4$)

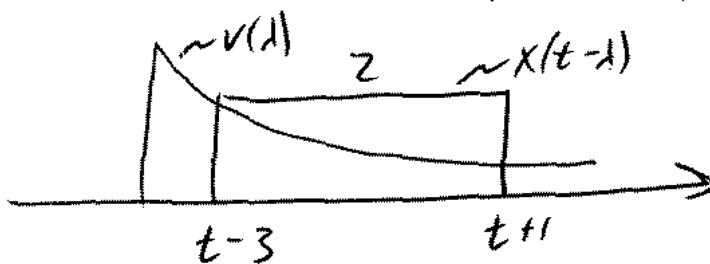
→ leading edge of $x(t-\lambda)$ overlaps $v(\lambda)$, but trailing edge does not overlap



$$\begin{aligned} x(t) * v(t) &= \int_1^{t+1} (2) 4e^{-2\lambda} d\lambda = \frac{8e^{-2\lambda}}{-2} \Big|_1^{t+1} \\ &= -4e^{-2(t+1)} + 4e^{-2(1)} = \underline{4e^{-2}(1 - e^{-2t})} \end{aligned}$$

3rd Interval ($t \geq 4$)

→ $x(t-\lambda)$ and $v(\lambda)$ fully overlap



$$\begin{aligned} x(t) * v(t) &= \int_{t-3}^{t+1} (2) 4e^{-2\lambda} d\lambda = \frac{8e^{-2\lambda}}{-2} \Big|_{t-3}^{t+1} \\ &= -4e^{-2(t+1)} + 4e^{-2(t-3)} \\ &= -4e^{-2t} e^{-2} + 4e^{-2t} e^6 \\ &= \underline{4e^{-2t}(e^6 - e^{-2})} \quad t \geq 4 \end{aligned}$$

```
% Chapter 2 problem 2.29e (p2_29e.m)
% Plot the convolution of
% x(t) = 2[u(t+1)-u(t-3)] with v(t) = 4e^{-2t}u(t-1).
% The analytic result is
%   x(t) * v(t) = 4e^{-2}[1-e^{-2t}] for 0 < t < 4 s
%   x(t) * v(t) = 4e^{-2t}[e^6-e^{-2}] for t > 4 s
%   x(t) * v(t) = 0 for all other t
clear;clc;close all;
% Calculate the analytic results
t0 = -3.5:0.05:0; t1 = 0:0.05:4; t2 = 4:0.05:9;
y0 = 0*t0;
y1 = 4*exp(-2)*(1-exp(-2*t1));
y2 = 4*exp(-2*t2)*(exp(6)-exp(-2));
t = [t0 t1 t2]; y = [y0 y1 y2];
%
plot(t,y, 'r-'), axis([-3.5 9 0 0.6]),
ylabel('y(t)', 'fontsize',16, 'fontname','times')
xlabel('t (s)', 'fontsize',16, 'fontname','times')
title({'Problem 2.29e y(t) = x(t)*v(t)';...
'x(t) = 2[u(t+1)-u(t-3)] and v(t) = 4e^{-2t}u(t-1)',...
'fontsize',18, 'fontname', 'times'})
text(-3,0.45, 'y(t) = 4e^{-2}[1-e^{-2t}]', 'fontsize',14, 'fontname', 'times')
text(4.5,0.45, 'y(t) = 4e^{-2t}[e^6-e^{-2}]', 'fontsize',14, 'fontname', 'times')
set(findobj('type','line'), 'linewidth',2, 'markersize',12)
set(findobj('type','axes'), 'linewidth',2, 'fontsize',14, 'fontname', 'times')
```

