# EE 313 Signals and Systems (Fall 2024) Project 1 Unit Pulse Response/Convolution Representation, Part B

#### Introduction

In this lab, we will examine finding the output of a discrete-time (DT) filter for a given input signal by convolution, i.e., convolve the input signal with the unit pulse response of the filter. In part A of the project, we designed a 6<sup>th</sup>-order Chebyshev Type I DT IIR LP filter based on an analog cutoff frequency  $f_c = 160$  Hz and passband ripple of R = 0.25 dB using a sampling period  $T_S = 1.5$  ms. This type of filter has an infinite impulse response (IIR). However, to implement the convolution representation, we will truncate the unit pulse response h[n] to be of length  $N_{\text{max}}$ , i.e.,  $0 \le n \le N_{\text{max}}$  -1. In essence, we will create a finite impulse response (FIR) DT LP filter based on the IIR DT LP filter.

### Project

- 1) Write an m-file to compute the unit pulse response h[n] of the filter for  $0 \le n \le N_{\text{max}}$  -1. Start with  $N_{\text{max}} = 101$ . The filter has no initial energy, i.e., y[n < 0] = 0. Then, perform the following tasks.
  - a) Using Matlab, create a stem plot of h[n] with a horizontal scale of  $-1 \le n \le N_{\text{max}} 1$  and a vertical scale from -0.3 to 0.5.
  - b) Also, create a stem plot of h[n] with a horizontal scale of  $-1 \le n \le 20$  and the same vertical scale. Find and label (value and index) the largest positive  $h_{pos}[n_{pos}]$  and negative  $h_{neg}[n_{neg}]$  swings in the unit pulse response on stem plot. At a minimum, labels should give the numerical value of stem with at least 3 significant figures. From the plot determine the maximum swing in the unit pulse response  $h_{max} = \max[h_{pos}[n_{pos}], |h_{neg}[n_{neg}]|$ .
  - c) Next, find  $h_{1\%}[n_{1\%}]$ , i.e., the point where the magnitude of the unit pulse response |h[n]| becomes (and stays) **less than** 1% of  $h_{\text{max}}$ , i.e.,  $0.01h_{\text{max}}$ , giving both value and index. Also, give the value and index  $h[n_{1\%} 1]$ , i.e., the last point in the unit pulse response which **exceeds** 1% of  $h_{\text{max}}$ . If necessary, increase  $N_{\text{max}}$ .
    - Hint: Create another figure to your m-file, using the plot() command, showing h[n] as dots with dashed horizontal lines at  $\pm 0.01h_{\text{max}}$ . Set the vertical scale to  $\pm 0.02h_{\text{max}}$  and change the horizontal scale as needed to 'zoom' in on  $h_{1\%}[n_{1\%}]$  and  $h[n_{1\%}-1]$ .
  - d) Is  $N_{\text{max}} = 101$  sufficient to find  $h_{1\%}[n_{1\%}]$ ? If so, use this value to create the FIR DT filter. If not, increase  $N_{\text{max}}$  by steps of 20 (e.g., 121, 141, ...) until  $h_{1\%}[n_{1\%}]$  is found. Give value of  $N_{\text{max}}$  used.
  - e) Using the stem plot of *h*[*n*], is the filter stable? Why?
  - f) Give a listing of the m-file.
  - **Hint:** To find h[n], you can use the 'recur' command. Remember to remove coefficient  $a_0 = 1$  from the coefficient vector a generated by cheby1() in order to match the recur() format. For example, add the line 'a(1) = [];' to your m-file after the cheby1() command. Or, the commands 'dimpulse' and 'filter' can be used (see MATLAB help).
- 2) Next, use DT convolution representation to calculate the output from the filter. The DT input signals  $v_{in}[n]$  should each be calculated for  $0 \le n \le 100$ . They are sampled from the continuous time (CT) voltage signal  $v_{in}(t) = V_0 \sin(2\pi f t) u(t)$  where  $V_0 = 100$  V and  $f = f_c/3$ ,  $f_c$ , 1.1  $f_c$ , and 1.25  $f_c$  (four separate inputs). The specific results required are:

- a) Analytically determine the index  $n_{acc}$  and corresponding time  $t_{acc} = n_{acc} T_S$  where the output signal  $v_{out}[n]$  ceases to be accurate (show work).
- b) At each frequency  $f = f_c/3$ ,  $f_c$ , 1.1  $f_c$ , and 1.25  $f_c$ , find and **tabulate** the expected maximum voltage magnitudes for the output  $v_{out}[n]$  after passing through the filter. Format: col. 1 f (Hz), col. 2  $V_0$  (V), col. 3 |H(f)|, and col. 4  $V_0 |H(f)|$  (V).

**Hint:** Ideally, the output signal should have a maximum magnitude of  $V_0|H(f)|$ . Use results from step 2f of Project 1, part A.

- c) Using the  $v_{out}[n]$  data, plot  $v_{out}(t)$  (solid line) versus time ( $t = n T_S$ ) for the **full length** of the 'conv' output at each of the specified frequencies f (**four** separate plots). Identify/label each plot by the appropriate frequency f. On each of the plots, put a labeled vertical dashed line at time  $t_{acc}$  and put labeled horizontal dashed lines at the voltage levels  $\pm V_0 |H(f)|$ .
- d) Over the accurate time range, examine the magnitude of  $v_{out}(t)$  at each of the specified frequencies. Does the DT filter work as expected? Comment on any anomalies, transitions, or other interesting features in the plots. [Prompts: In light of  $v_{out}(t)$  shown in the plots, roughly how long  $\Delta t_{SS}$  does it take for the filter to start working or reach a steady-state? After  $t_{acc}$ , roughly how long  $\Delta t_{stop}$  does it take for the output to die off? In light  $\Delta t_{SS}$  and  $\Delta t_{stop}$ , roughly how many points would these correspond with in the unit pulse response h[n]? Discuss pros and cons of digital versus analog filters.]
- e) Give a listing of the m-file.

### Hints:

- ▶ Use MATLAB 'conv' command to calculate  $v_{out}[n] = v_{in}[n] * h[n]$ .
- ▶ Remember the sampled signal is  $v_{in}[n] = v_{in}(t_n = nT_s) = V_0 \sin(2\pi f nT_s) u(nT_s)$ .
- > The sampling rate  $T_s$  and how it 'lines up' with each frequency will determine whether or how often the sampling 'hits' the exact minima and maxima of the signals.

## Project report format

The results should be organized into a word-processed short report.

- In addition to syllabus HW format requirements, use font size  $\geq 12$  points and line spacing  $\geq 1.1$ .
- Include: 1) cover page, 2) Introduction, 3) body (broken down into subsections based on the steps in project), and 4) Summary & Conclusions.
- Put the calculations, results, m-files, and plots/figures in the body of the report in the order specified as they occur. Do not use appendices.
- On all plots, label horizontal and vertical axes, and insert a horizontal axis at 0. Put "EE 313, Project # & part #, *your initials*, date" in the title.
- Numerical results that are specifically requested should be put on separate line(s), not 'buried' in the middle of a paragraph.
- To enhance readability, figures/plots should span width of page and face either the bottom or right of page. Also, remember that text on figures/plots that is too small to read might as well not exist.
- For all m-files, put the filename, EE 313, Project # & part #, your name, and date in comment lines.
- Staple results together and turn-in the project report on Wednesday, October 16, 2024.