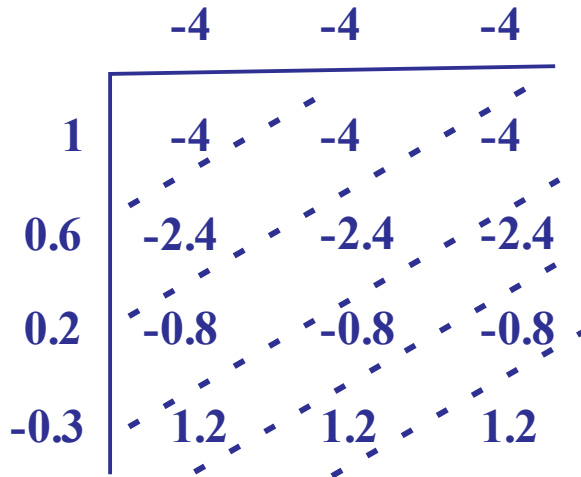


EE 313 Signals and Systems (Fall 2024) Examination 1

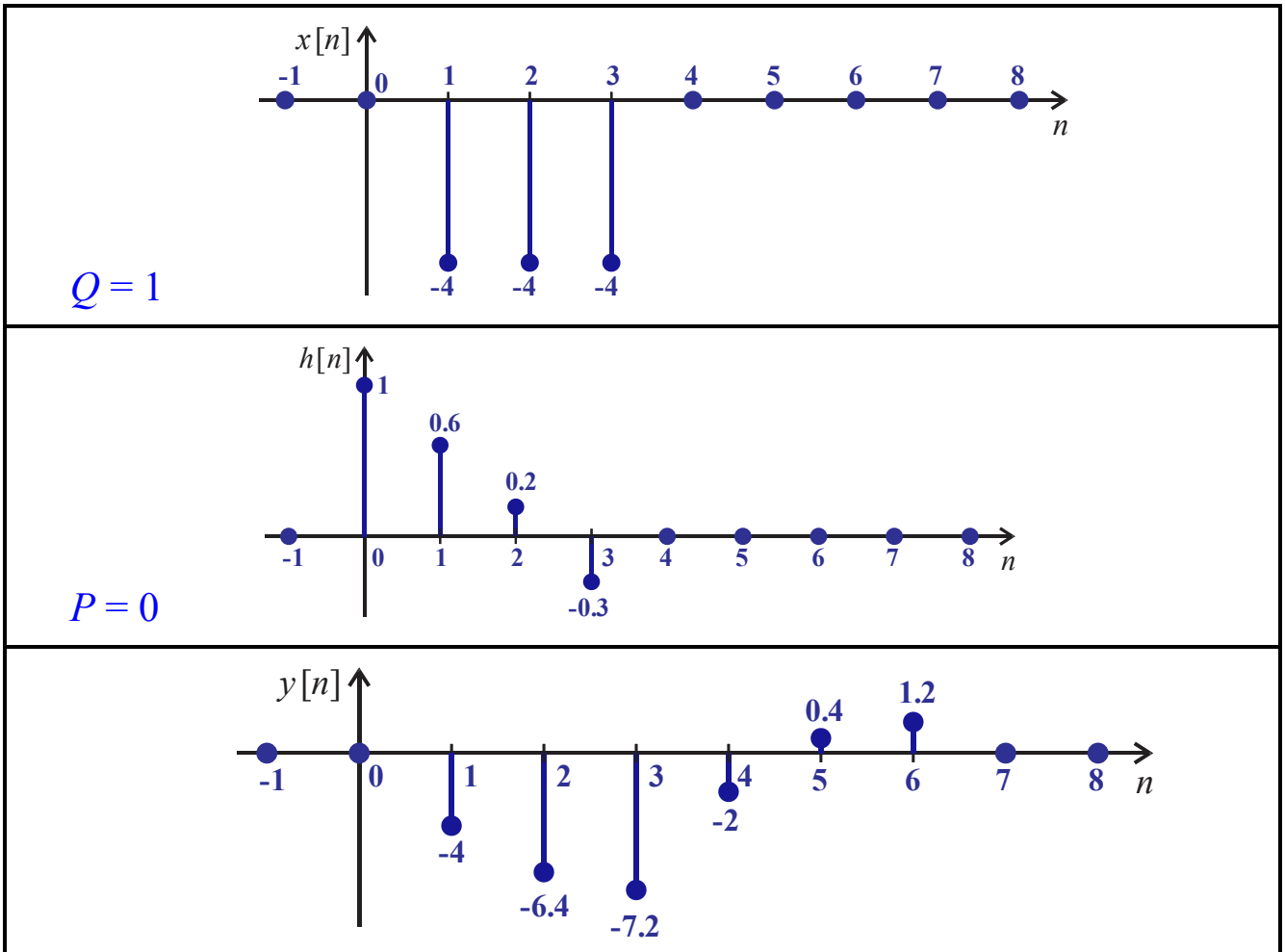
Name KEYA

Instructions: Show all work for full credit. Write answers in indicated places. Insert equation sheet inside exam.

- 1) A discrete-time signal $x[n] = -4p_3[n-2]$ is fed into a system with a unit-pulse response given by $h[n] = \delta[n] + 0.6\delta[n-1] + 0.2\delta[n-2] - 0.3\delta[n-3]$. Compute the output $y[n]$ from the system. Then, in the indicated places, sketch labeled stem plots of $x[n]$, $h[n]$, and $y[n]$ for $-1 \leq n \leq 8$.



$P + Q = 0 + 1 = 1$
 $y[1] = -4$
 $y[2] = -4 - 2.4 = -6.4$
 $y[3] = -4 - 2.4 - 0.8 = -7.2$
 $y[4] = -2.4 - 0.8 + 1.2 = -2$
 $y[5] = -0.8 + 1.2 = 0.4$
 $y[6] = 1.2$
 $y[n] = 0$ for all other n



2) Answer/solve the following questions/problems.

- a) Is the discrete-time function $w[n] = 25 \cos(5n - 0.2\pi)$ **periodic** or **non-periodic**? (correct answer) **Show** why or why not.

From $w[n]$ equation, the DT frequency $\Omega = 5$. Per section 1.2.4, if $\Omega/2\pi = 5/2\pi = q/r$, an integer ratio, the function $w[n]$ is periodic. Since π is irrational, the ratio cannot be put in terms of the ratio of integers \Rightarrow **w[n] is non-periodic.**

- b) Given the system output $y(t) = -4t^2x(t) + 2x(t-2.2)$ for an input $x(t)$, is the system **additive** or **non-additive**? (correct answer) **Show** why or why not.

For input $x_1(t)$, $y_1(t) = -4t^2x_1(t) + 2x_1(t-2.2)$.

For input $x_2(t)$, $y_2(t) = -4t^2x_2(t) + 2x_2(t-2.2)$.

For input $x_1(t) + x_2(t)$, $\tilde{y}(t) = -4t^2[x_1(t) + x_2(t)] + 2[x_1(t-2.2) + x_2(t-2.2)] = y_1(t) + y_2(t)$

\Rightarrow **system is additive.**

- c) Given the system output $y(t) = -4t^2x(t) + 2x(t-2.2)$ for an input $x(t)$, is the system **homogenous** or **inhomogeneous**? (correct answer) **Show** why or why not.

Note that $ay(t) = a[-4t^2x(t) + 2x(t-2.2)]$.

For input $ax(t)$, $\tilde{y}(t) = -4t^2[ax(t)] + 2[ax(t-2.2)] = a[-4t^2x(t) + 2x(t-2.2)] = ay(t)$

\Rightarrow **system is homogeneous.**

- d) Given the system output $y(t) = -4t^2x(t) + 2x(t-2.2)$ for an input $x(t)$, is the system **linear** or **nonlinear**? (correct answer) **Show** why or why not.

Since the system is **additive and homogenous** \Rightarrow **system is linear.**

- e) Is the system described by $w(t) = 8t^2x(t-1) - 4x(t+2.2)$ **causal** or **noncausal**? Does the system have **memory** or is it **memoryless**? (correct answers)

Why or why not?

System is **noncausal** because of the $x(t+2.2)$ term depending on a future value of the input $x(t)$.

System has **memory** as evidenced by the $x(t-1)$ term depending on a past value of the input $x(t)$.

- 3) A linear, time-invariant series *RLC* circuit has response $y(t) = 4.5 + 1.5e^{-4t} - 6e^{-2t}$ (V) for $t \geq 0$ to the input $x(t) = 0.25u(t)$ (V) when initially at rest. Determine the unit step response $g(t)$ and the impulse response $h(t)$ of this circuit. With the system initially at rest, determine the system output $y_1(t)$ to the input $x_1(t) = 6u(t-3)$ (V) and find $y_1(t=4\text{ s})$

Note that $4x(t) = u(t)$.

$$\Rightarrow \text{By linearity, } g(t) = 4y(t) = 4[4.5 + 1.5e^{-4t} - 6e^{-2t}] = 18 + 6e^{-4t} - 24e^{-2t} \text{ (V) for } t \geq 0,$$

$$\text{or } g(t) = [18 + 6e^{-4t} - 24e^{-2t}]u(t) \text{ (V).}$$

$$\text{From notes, } h(t) = \frac{d g(t)}{dt} = 0 + 6(-4)e^{-4t} - 24(-2)e^{-2t} = -24e^{-4t} + 48e^{-2t} \text{ (V/s) for } t > 0,$$

$$\text{or } h(t) = [-24e^{-4t} + 48e^{-2t}]u(t) \text{ (V/s).}$$

Using the convolution representation,

$$y_1(t) = x_1(t) * h(t) = 6u(t-3) * (-24e^{-4t} + 48e^{-2t})u(t).$$

However, that would be the **hard way** to find the answer.

An **easier** solution method is to note that input $x_1(t) = 6u(t-3)$ is a weighted and time-shifted unit step function. Using **linearity and time-invariance on the unit step response $g(t)$** ,

$$y_1(t) = 6g(t-3) = 6[18 + 6e^{-4t} - 24e^{-2t}]u(t) \Big|_{t \rightarrow t-3}$$

$$= [108 + 36e^{-4(t-3)} - 144e^{-2(t-3)}]u(t-3) \text{ (V) .}$$

$$= [108 + 36e^{12}e^{-4t} - 144e^6e^{-2t}]u(t-3) \text{ (V)}$$

Evaluating $y_1(t)$ at $t = 4$ s, yields

$$y_1(t=4\text{ s}) = [108 + 36e^{-4(4-3)} - 144e^{-2(4-3)}]u(4-3) \text{ (V)}$$

$$= [108 + 36e^{-4} - 144e^{-2}](1)$$

$$= 89.17108 \text{ (V)}$$

$$g(t) = \underline{[18 + 6e^{-4t} - 24e^{-2t}]u(t) \text{ (V)}}$$

$$h(t) = \underline{[-24e^{-4t} + 48e^{-2t}]u(t) \text{ (V/s)}}$$

$$y_1(t) = \underline{[108 + 36e^{-4(t-3)} - 144e^{-2(t-3)}]u(t-3) \text{ (V)}}$$

$$y_1(t=4\text{ s}) = \underline{89.17108 \text{ (V)}}$$

- 4) Using backward difference approximations, discretize the differential equation $1.8 \frac{d^2 y(t)}{dt^2} - 6 \frac{dy(t)}{dt} + 3y(t) = 9x(t)$ for $t \geq 0$ given a sampling rate $T = 0.3$ s and input $x(t) = 2u(t)$. Put the resulting difference equation in recursive form, i.e., $y[n] = -\sum_{i=1}^N a_i y[n-i] + \sum_{i=0}^M b_i x[n-i]$, and list the range of the index n . Given that $y(0) = -2$ and $\left. \frac{dy(t)}{dt} \right|_{t=0} = -4$, determine the discrete-time initial conditions. Calculate the system output $y[n]$ at $n = 2$.

Discretizing the I/O differential equation for an input $x(t) = 2u(t)$, yields

$$1.8 \left[\frac{y[n] - 2y[n-1] + y[n-2]}{T^2} \right] - 6 \left[\frac{y[n] - y[n-1]}{T} \right] + 3y[n] = 9x[n] = 9(2u[n]) = 18u[n].$$

Substituting in $T = 0.3$ s and doing some algebra, yields

$$(20 - 20 + 3)y[n] + (-40 + 20)y[n-1] + 20y[n-2] = 18u[n].$$

Then, putting this I/O difference equation into recursive form yields

$$y[n] = \frac{20}{3} y[n-1] - \frac{20}{3} y[n-2] + 6u[n] = 6.\overline{66} y[n-1] - 6.\overline{66} y[n-2] + 6u[n] \text{ for } n \geq 1.$$

Next, we need to find the discrete-time initial conditions.

Discretizing $y(0) = -2 \Rightarrow \underline{y[0] = -2} \Rightarrow y[n]$ recursion is good for $n \geq 1$.

Discretizing $\left. \frac{dy(t)}{dt} \right|_{t=0} = -4$ yields

$$\left. \frac{y[0] - y[-1]}{T} \right|_{T=0.3} = \frac{-2 - y[-1]}{0.3} = -4 \Rightarrow \underline{y[-1] = -0.8}.$$

Using recursion,

$$\text{For } n = 1, y[n=1] = y[1] = \frac{20}{3} y[1-1] - \frac{20}{3} y[1-2] + 6u[1] = 6.\overline{66}(-2) - 6.\overline{66}(-0.8) + 6 = -2.$$

$$\text{For } n = 2, y[n=2] = y[2] = \frac{20}{3} y[2-1] - \frac{20}{3} y[2-2] + 6u[2] = 6.\overline{66}(-2) - 6.\overline{66}(-2) + 6 = 6.$$

$$y[n] = \underline{6.\overline{66} y[n-1] - 6.\overline{66} y[n-2] + 6u[n]} \text{ for } n \geq 1$$

Discrete-time initial conditions: $\underline{y[0] = -2}$ and $\underline{y[-1] = -0.8}$ $y[2] = \underline{6}$